

Elastic properties of a chopped fiber reinforced composite

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In this example, we want to compute the elastic properties of a chopped fiber reinforced composite made of isotropic elastic matrix and transversely isotropic elastic fiber. The MSG solid model is used to predict the effective elastic properties of the 3D SG. We will consider a matrix cell of dimensions 10 mm x 10 mm x 10 mm and ten chopped fibers of radius 1 mm and length 8 mm to have a fiber volume fraction of 0.25. The fiber and matrix material properties are given in the table below.

Fiber properties defined as transversely isotropic elastic

E1 (MPa)	E2 (MPa)	G12 (MPa)	G23 (MPa)	ν_{12}	ν_{23}	α_{11} (u/°C)	α_{22} (u/°C)
2,33,000.00	15,000.00	8,963.00	,5639.00	0.23	0.33	-0.54	10.08

Isotropic Matrix properties

E (MPa)	ν	α (u/°C)
3,500.00	0.30	60.00

Material Properties

The orientation of the individual fibers with respect to the origin of the model are given in terms for translation coordinates and rotational degrees for all three axes in the table below.

The fiber orientation is given by fiber translation along the three axes (in mm) denoted by X,Y & Z and rotation along the three axes (in °) denoted by θ_x , θ_y , & θ_z .

Fiber No	X	Y	Z	θ_x	θ_y	θ_z
1	2.9	3.4	1.0	-3	5	0
2	0.6	3.1	0.8	0	0	0
3	-4.0	3.0	1.0	-6	7	0
4	-1.5	1.5	1.8	-4	0	0
5	3.5	1.1	1.3	16	0	0
6	1.5	1.0	1.7	0	-6	60
7	2.3	-3.7	1.2	0	9	0
8	-1.0	-2.6	1.4	3	-12	30
9	-3.6	1.7	1.4	6	0	16
10	-3.4	-3.0	0.7	0	0	0

Fiber orientation

Software Used

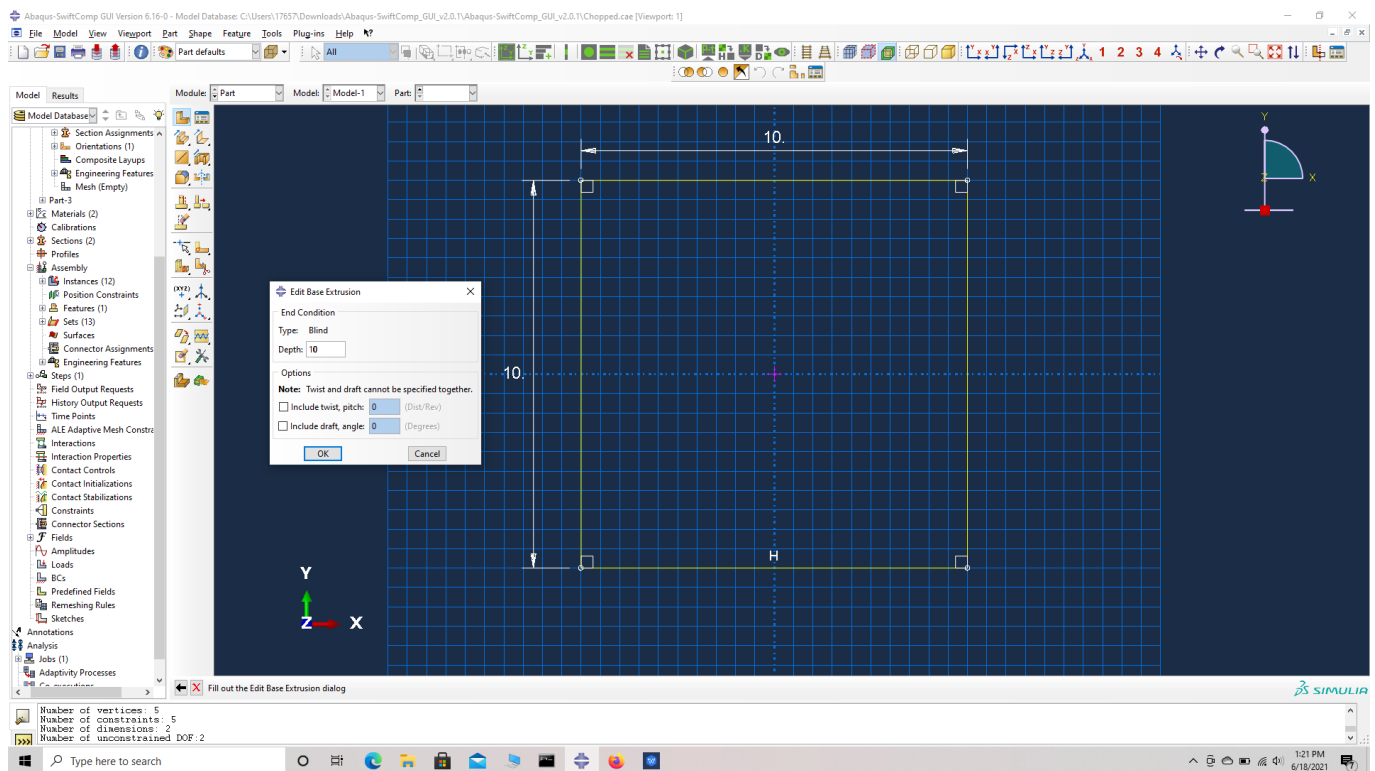
We will use SwiftComp 2.1 and Abaqus CAE with the Abaqus SwiftComp GUI for this tutorial. Abaqus CAE will be used to model the 3D SG while SwiftComp will be used to run the elastic homogenization in the background.

Solution Procedure

The problem is solved in the following steps:

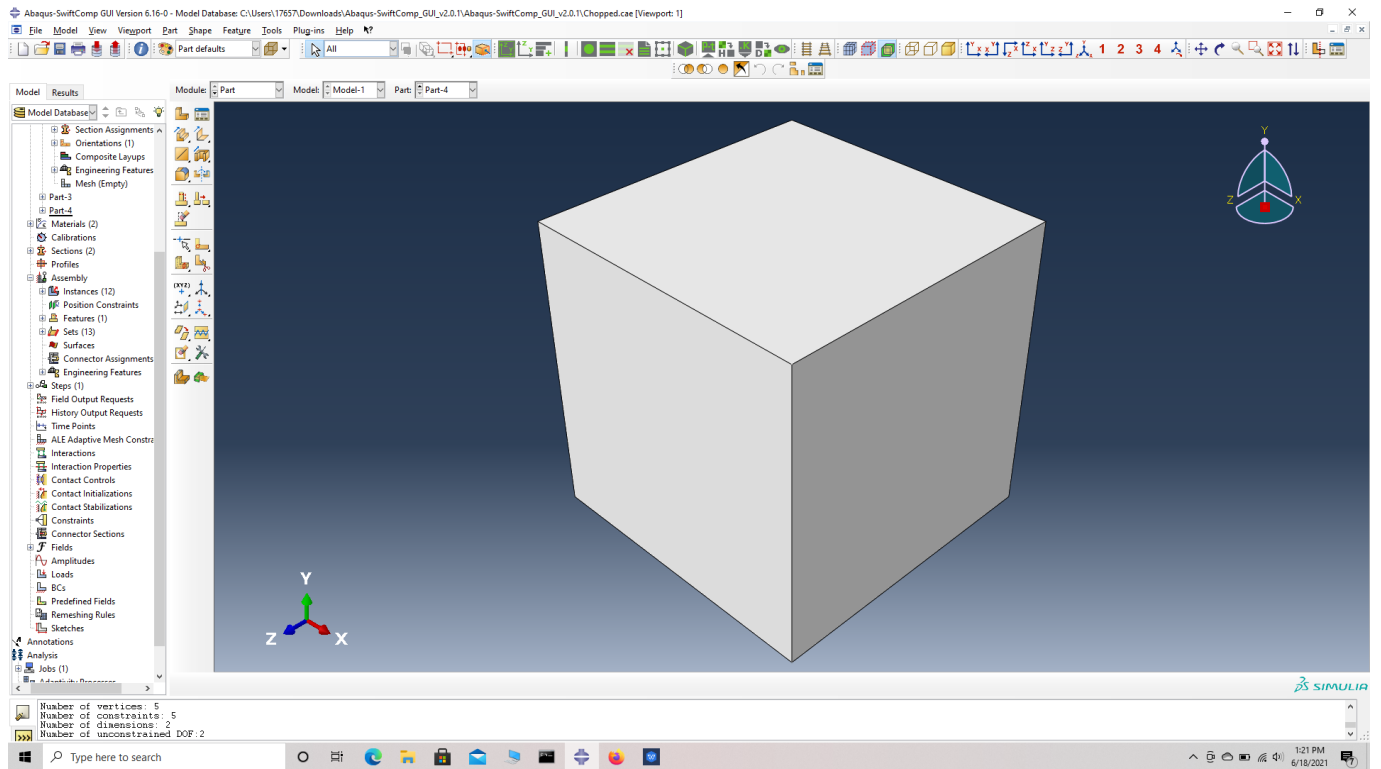
We will first create the matrix cell.

Step 1. Go to create part -> Create a 3D solid extrusion -> Sketch the cross section as a 10 mm x 10 mm square with the origin at the center. Extrude the part to a length of 10 mm so the origin is at the center of one side. This will help in the assembly.



Part dimensions

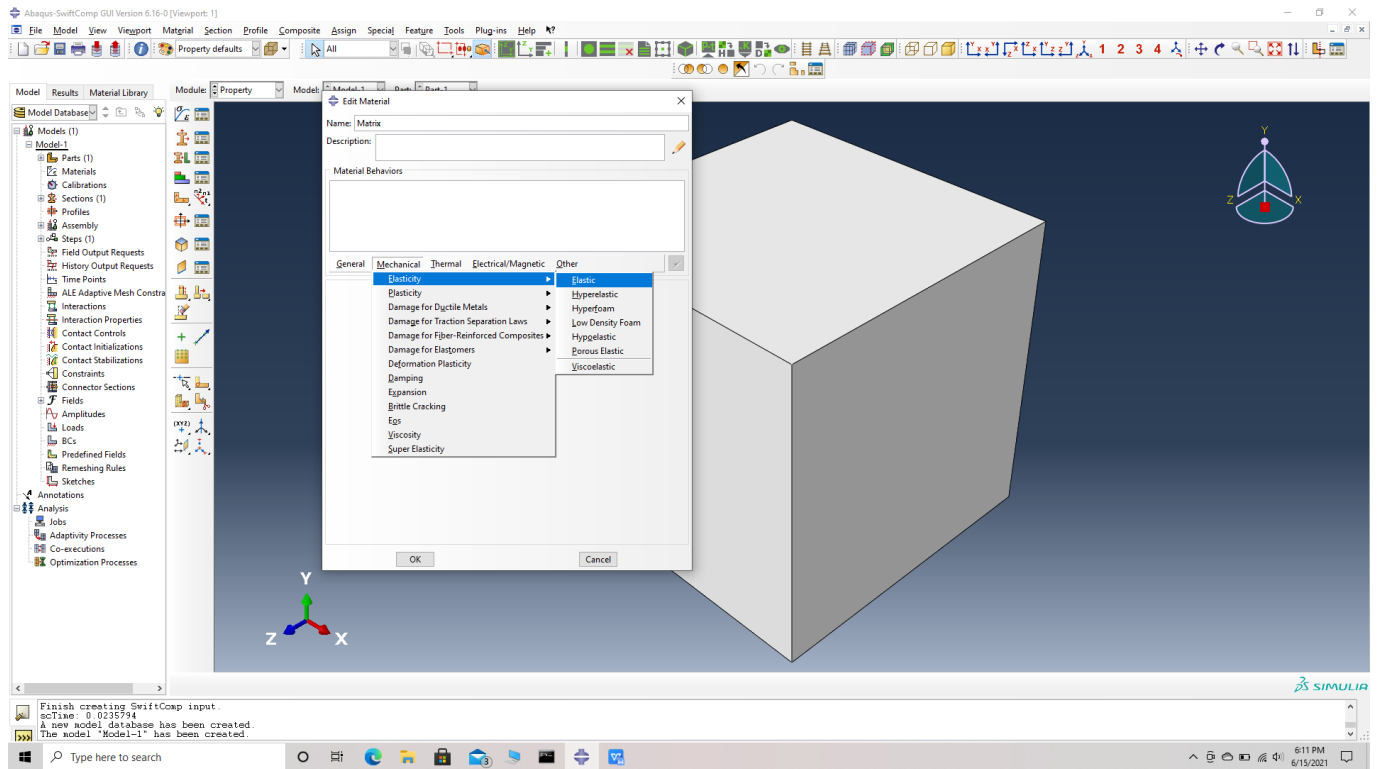
ELASTIC PROPERTIES OF A CHOPPED FIBER REINFORCED COMPOSITE



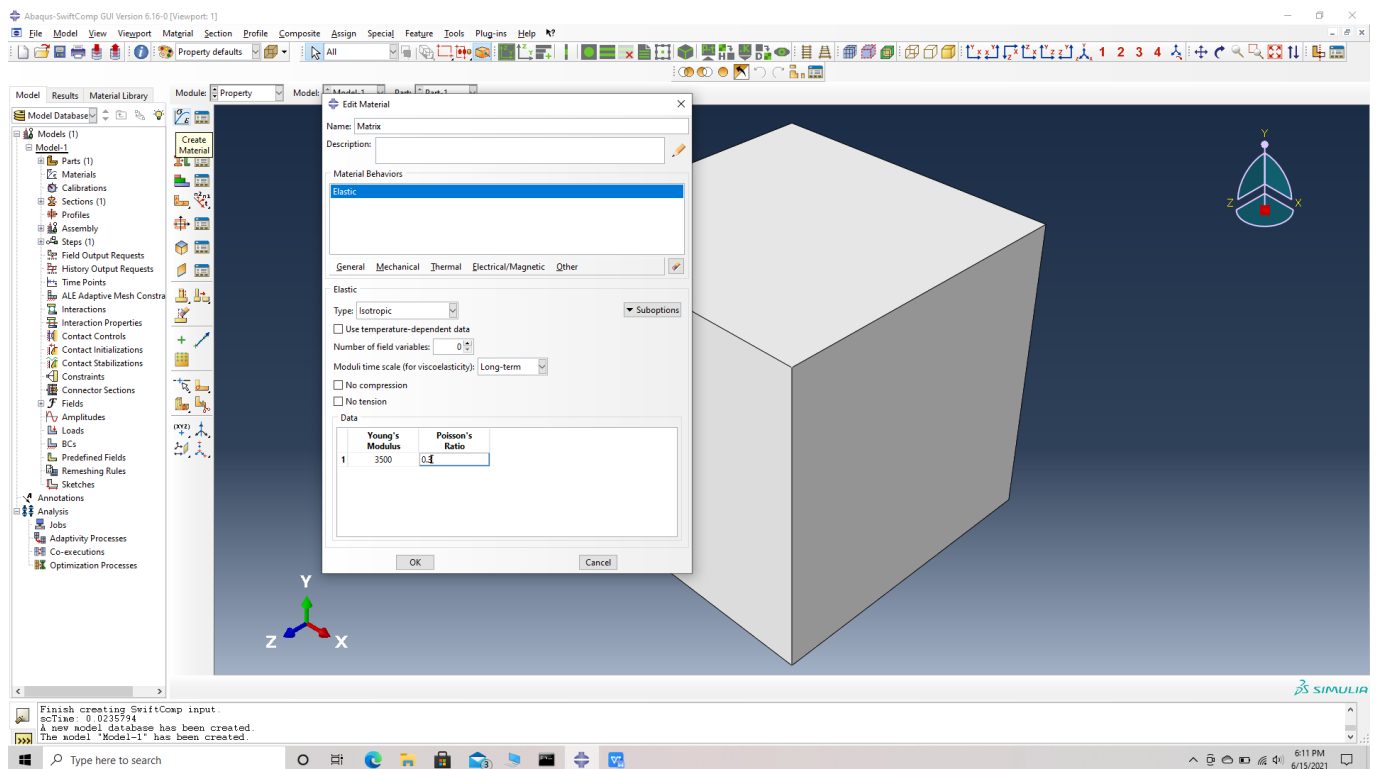
Part Geometry

Step 2. Enter the material properties for the model. First we need to choose the material properties from the matrix property table. Within the Materials section of Abaqus CAE, we create an elastic isotropic material called “Matrix” and add the corresponding properties.

ELASTIC PROPERTIES OF A CHOPPED FIBER REINFORCED COMPOSITE



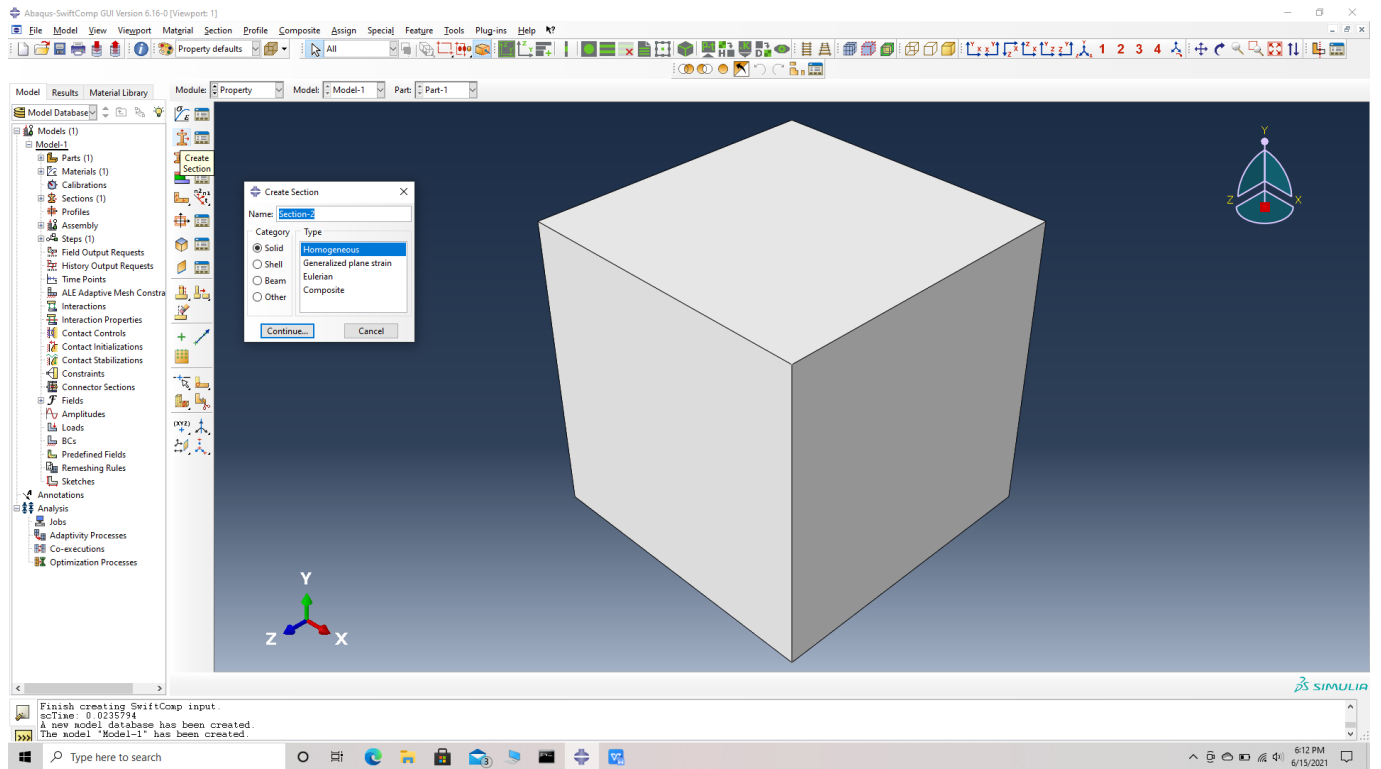
Material properties



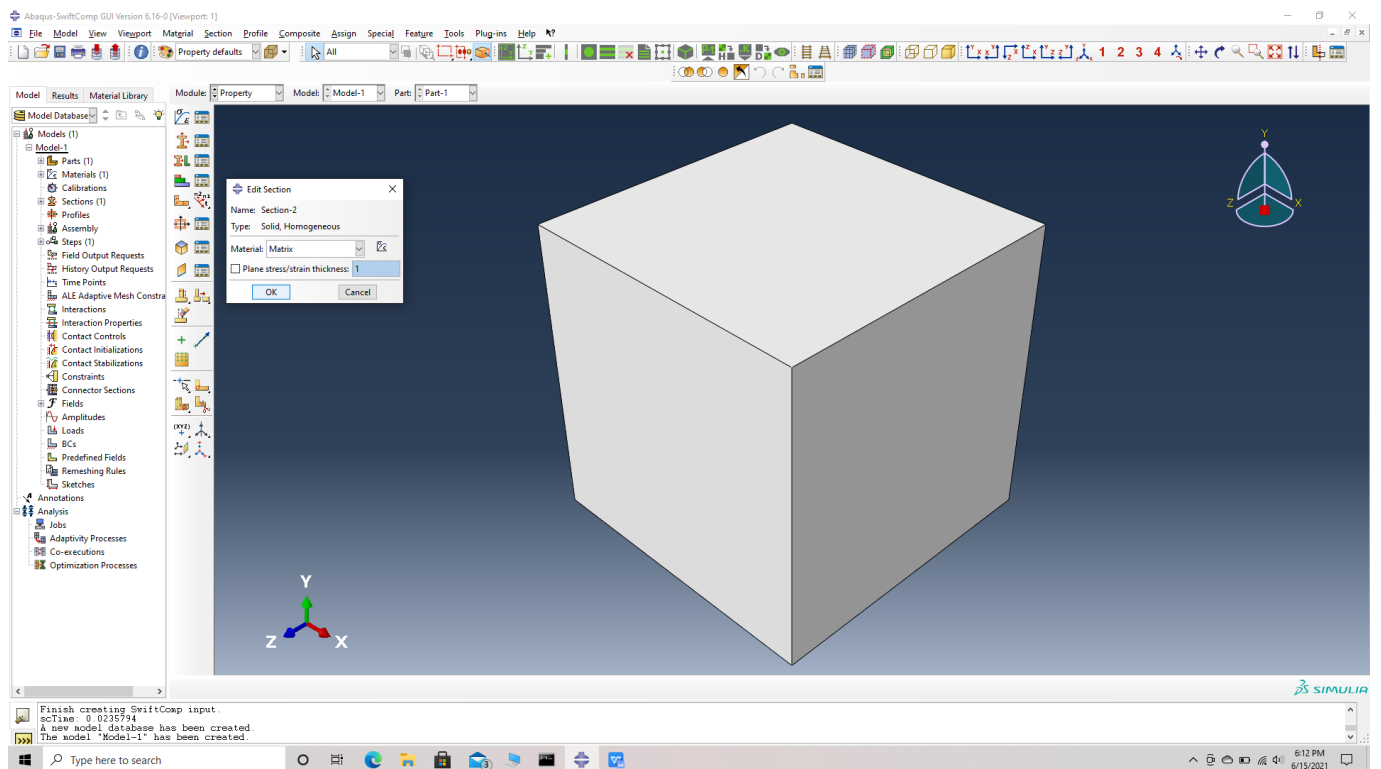
Material properties

Step 3. Create a homogeneous section, Section 1 for the matrix using the create section option.

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Create a section

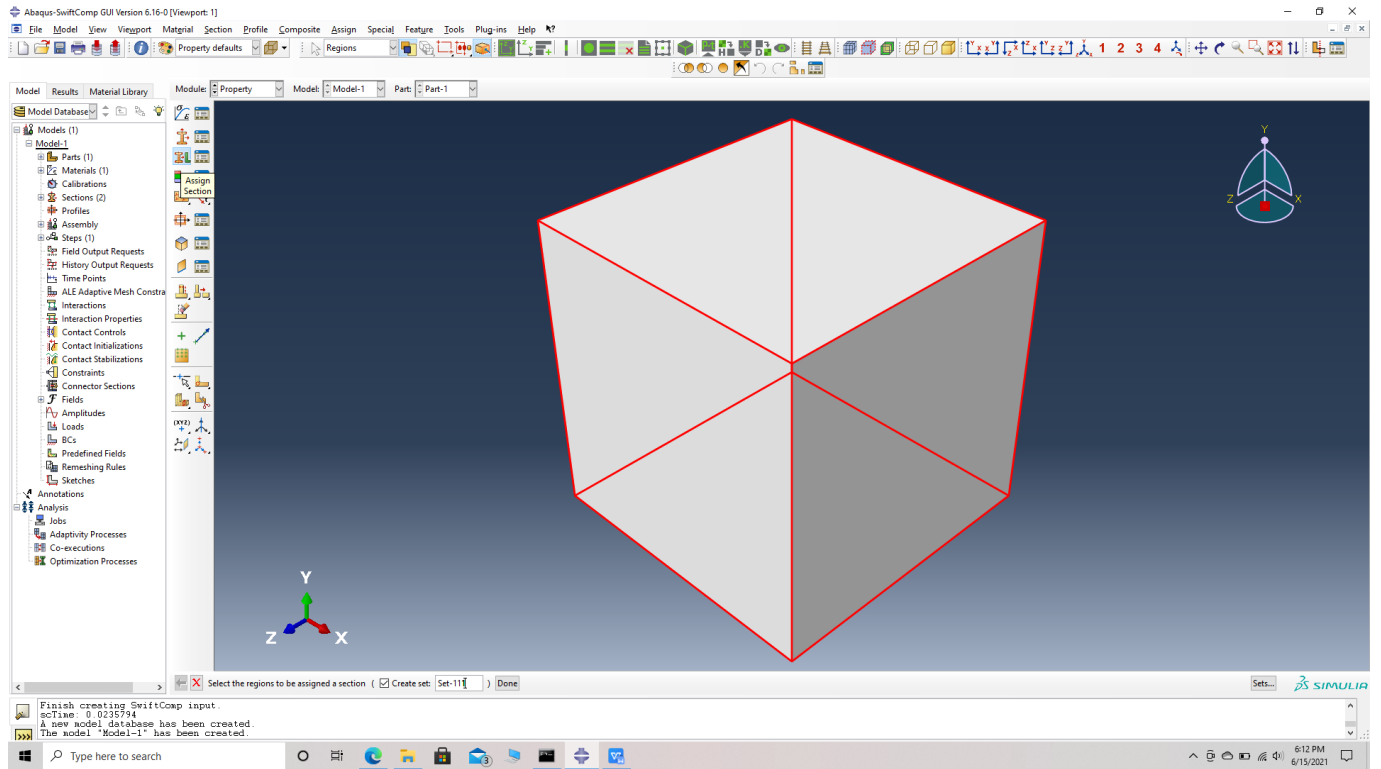


Assigning the material Matrix

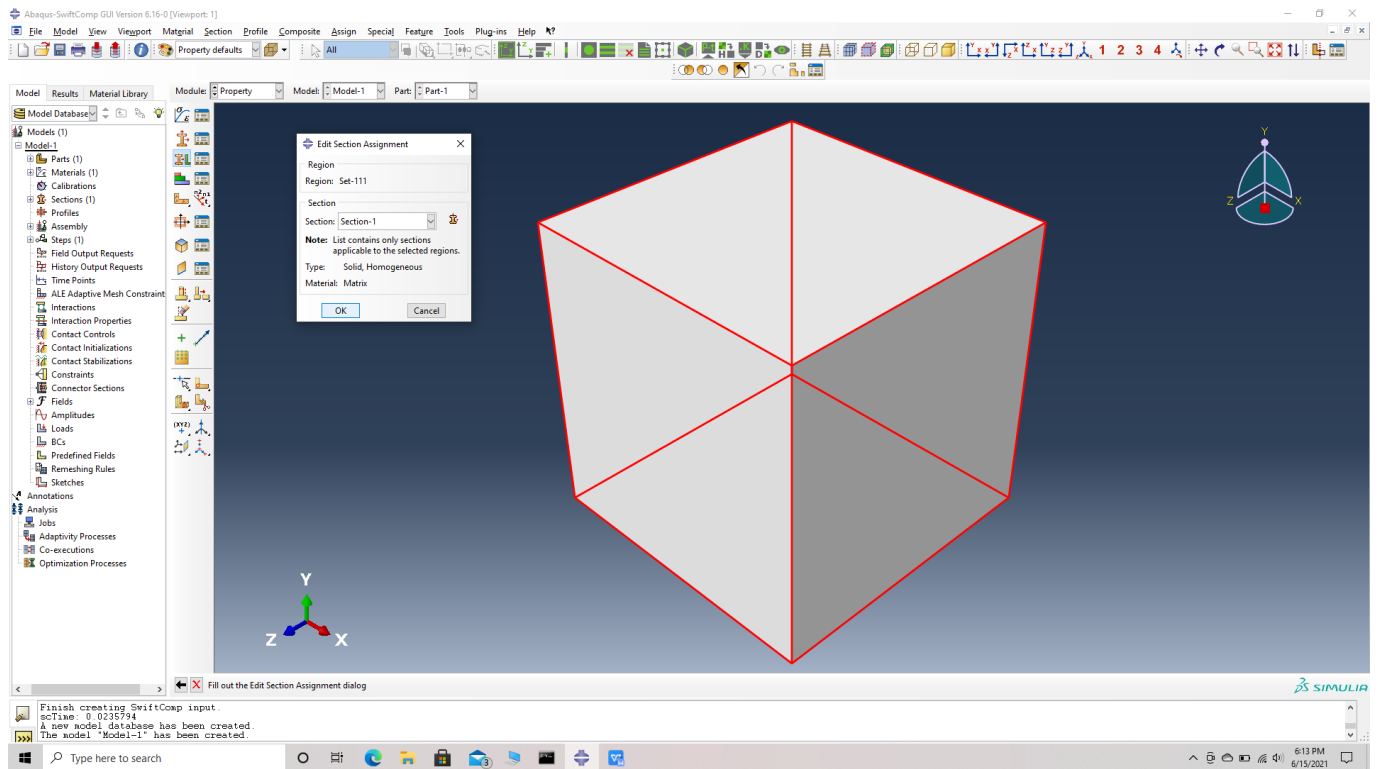
Step 4. Assign the section , Section 1 for the matrix cell using the assign section option. Name the set as Set-111 to differentiate different sets for different parts. Abaqus automatically

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assigns set- name for all parts as Set -1.



Assign a set

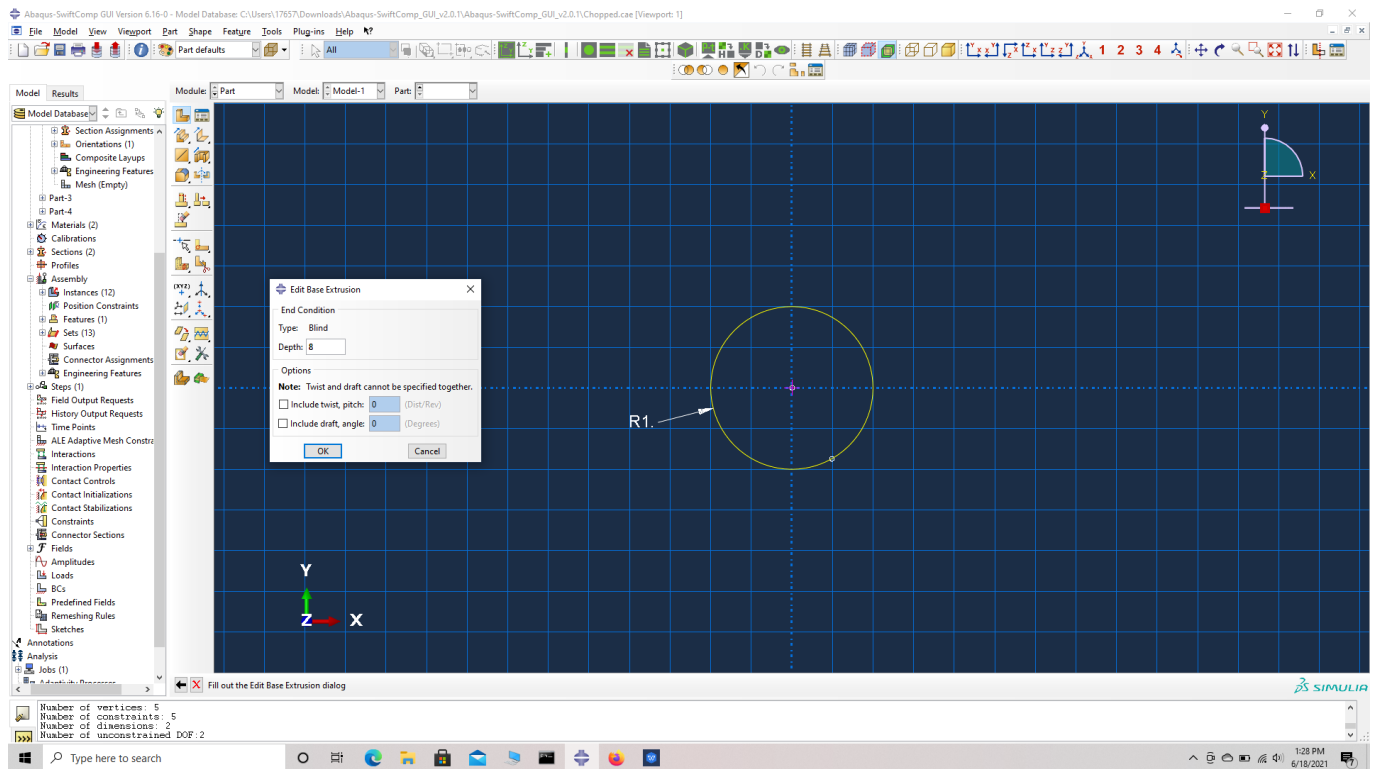


Assign Section for Set

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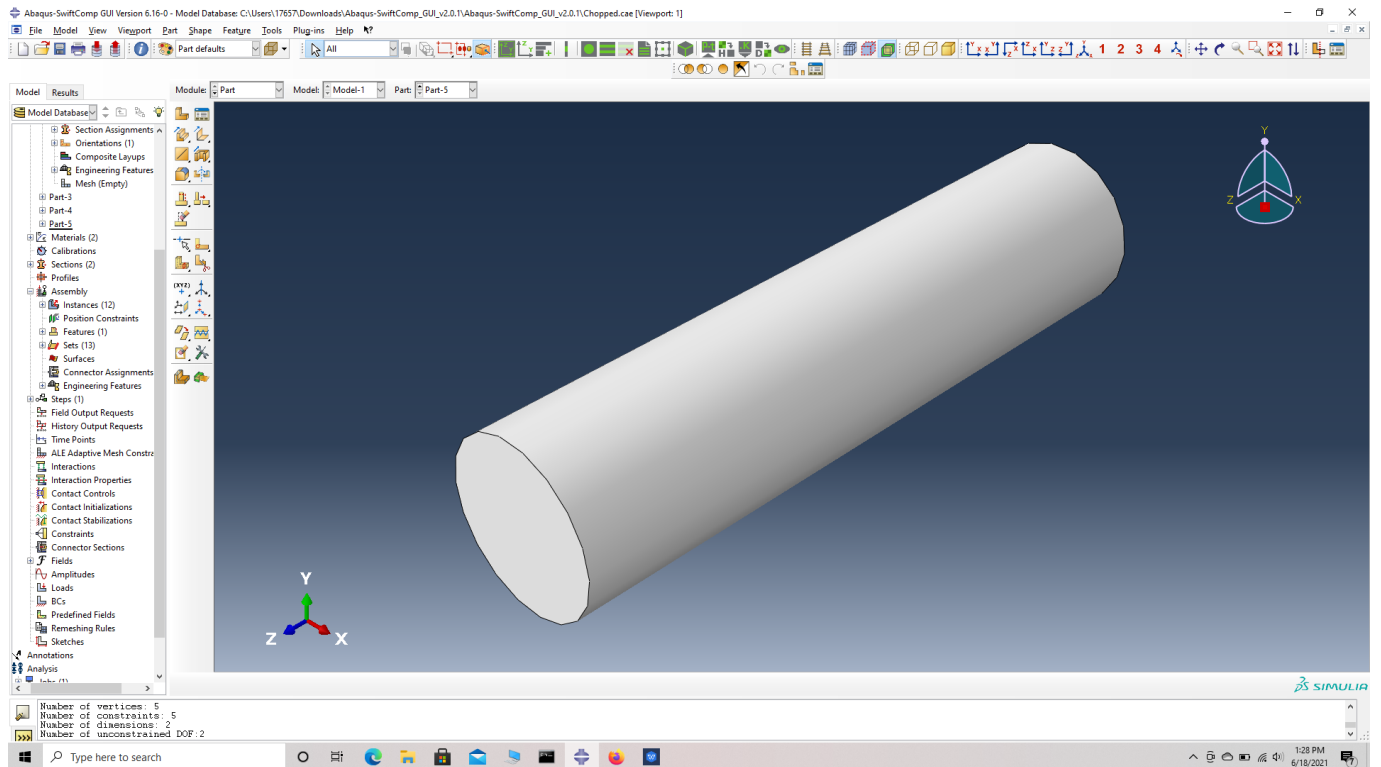
We will first create the chopped fiber

Step 5. Go to create part -> Create a 3D solid extrusion -> Sketch the cross section as a circle of radius 1 mm with the origin at the center. Extrude the part to a length of 8 mm so the origin is at the center of one side. This will help in the assembly.



Part dimensions

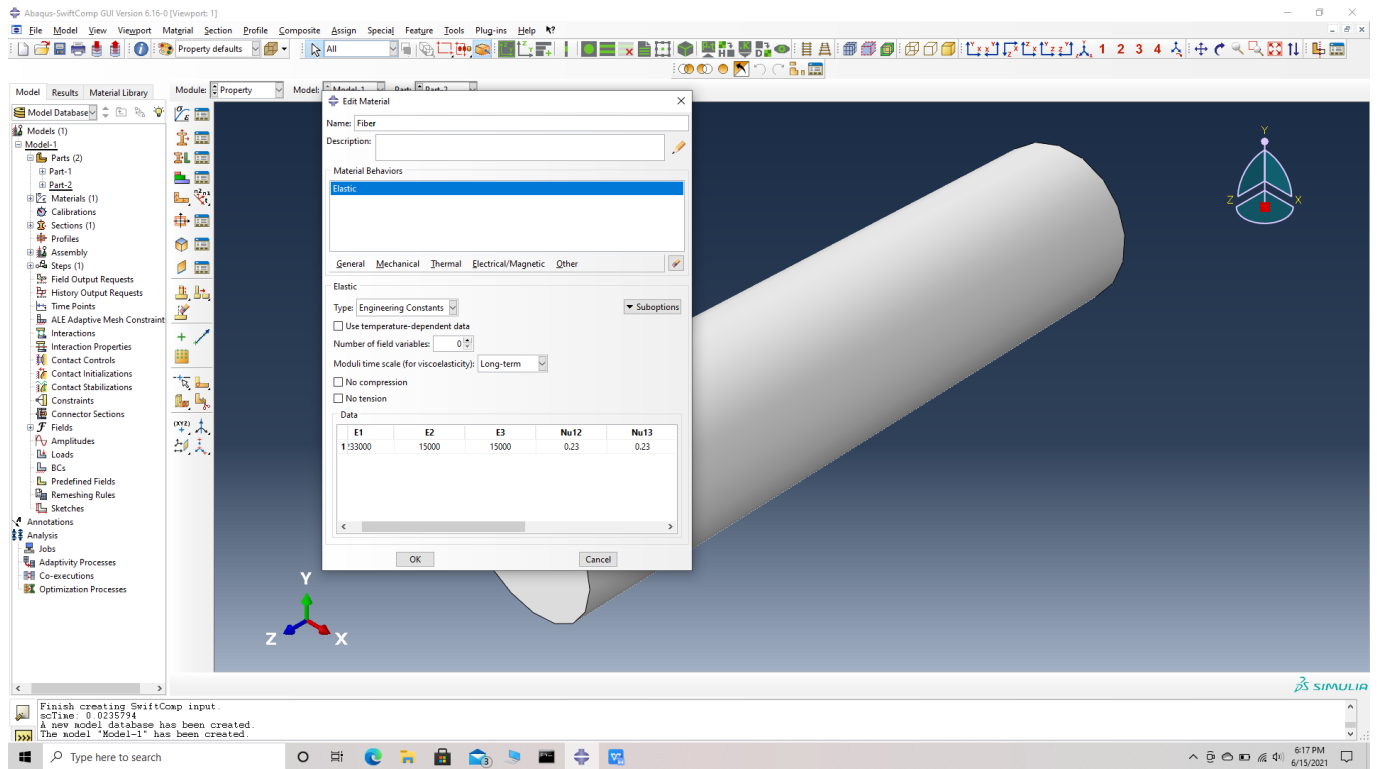
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Part Geometry

Step 6. Enter the material properties for the model. First we need to choose the material properties from the fiber property table. Within the Materials section of Abaqus CAE, we create a elastic material called “Fiber” and add the corresponding properties s engineering constants.

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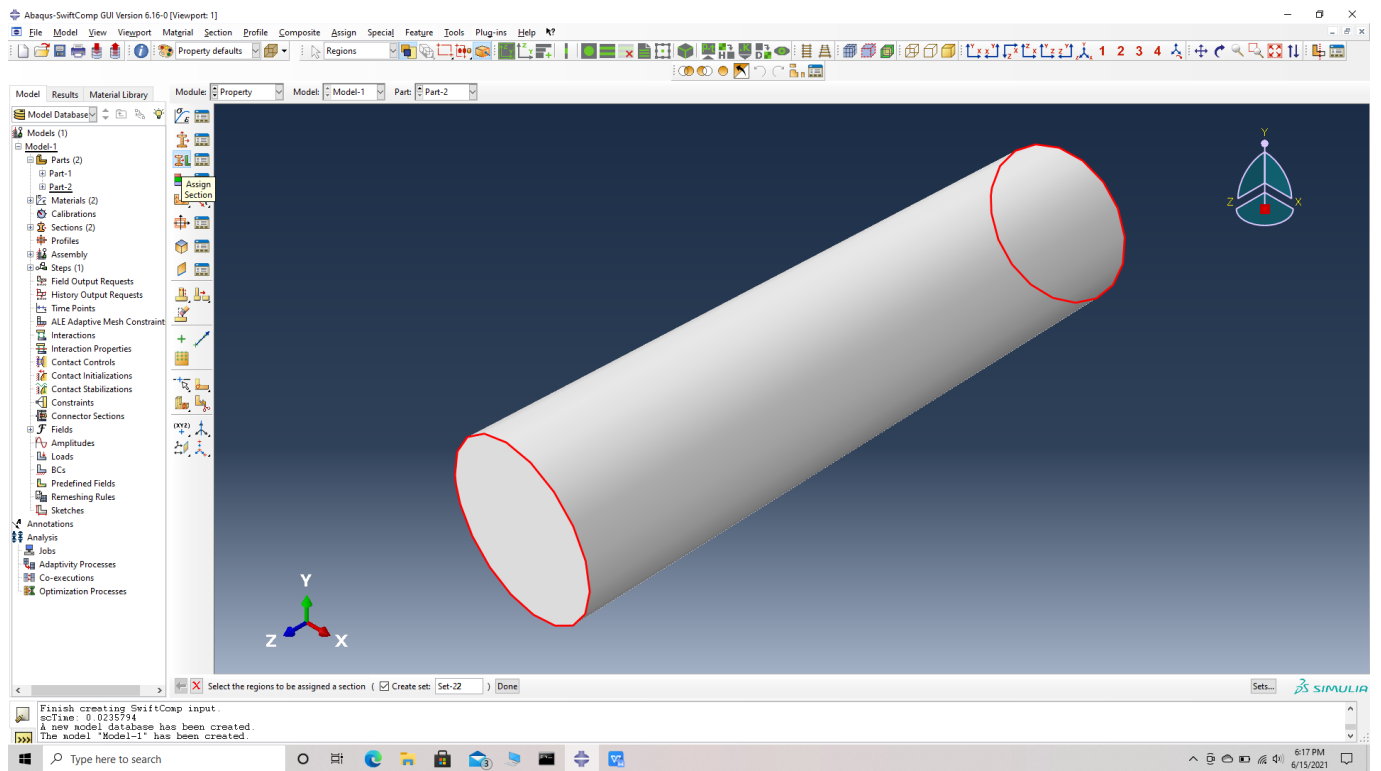


Material properties

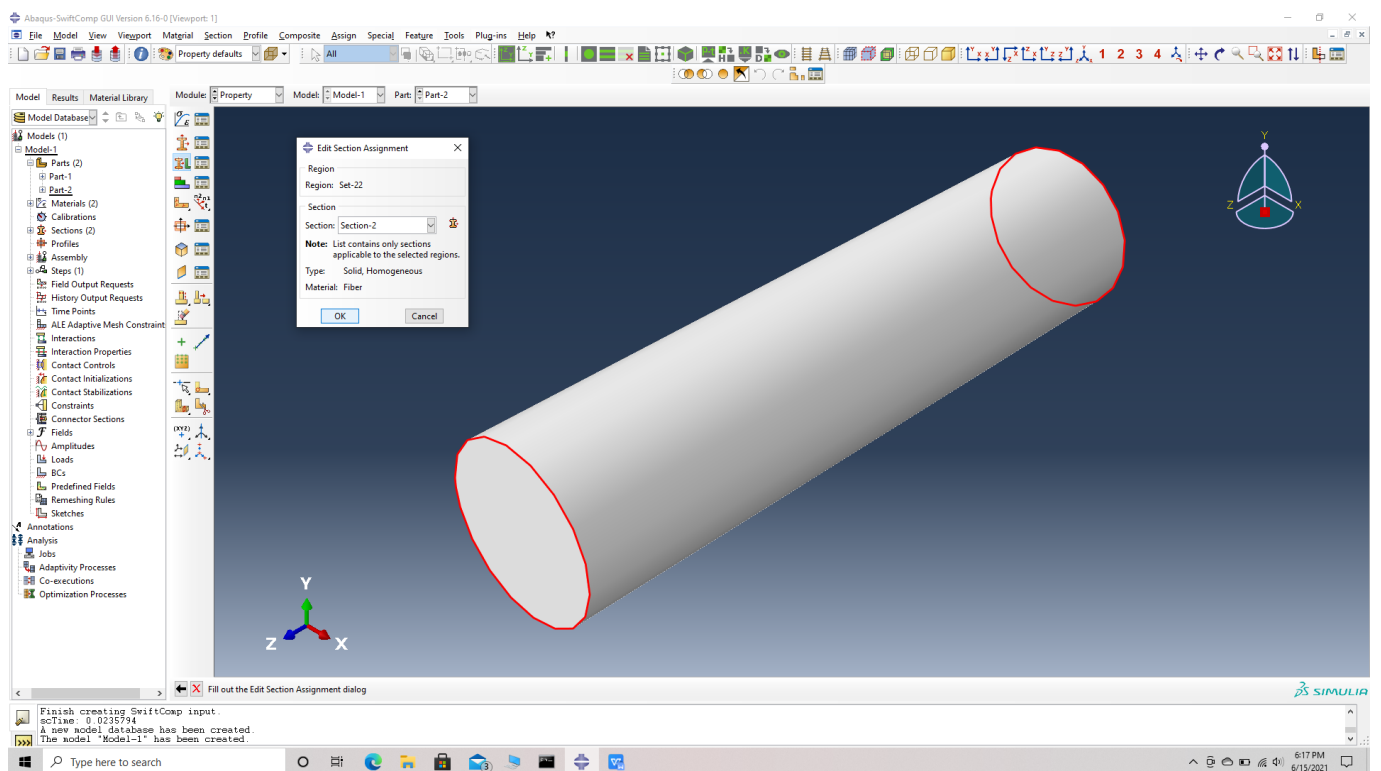
Step 7. Create a solid homogeneous section, Section 2 for the fiber using the create section option.

Step 8. Assign the section, Section 2 for the fiber using the assign section option. Name the set as Set-22 to differentiate different sets for different parts. Abaqus automatically assigns set-name for all parts as Set -1.

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Assign a set to the model

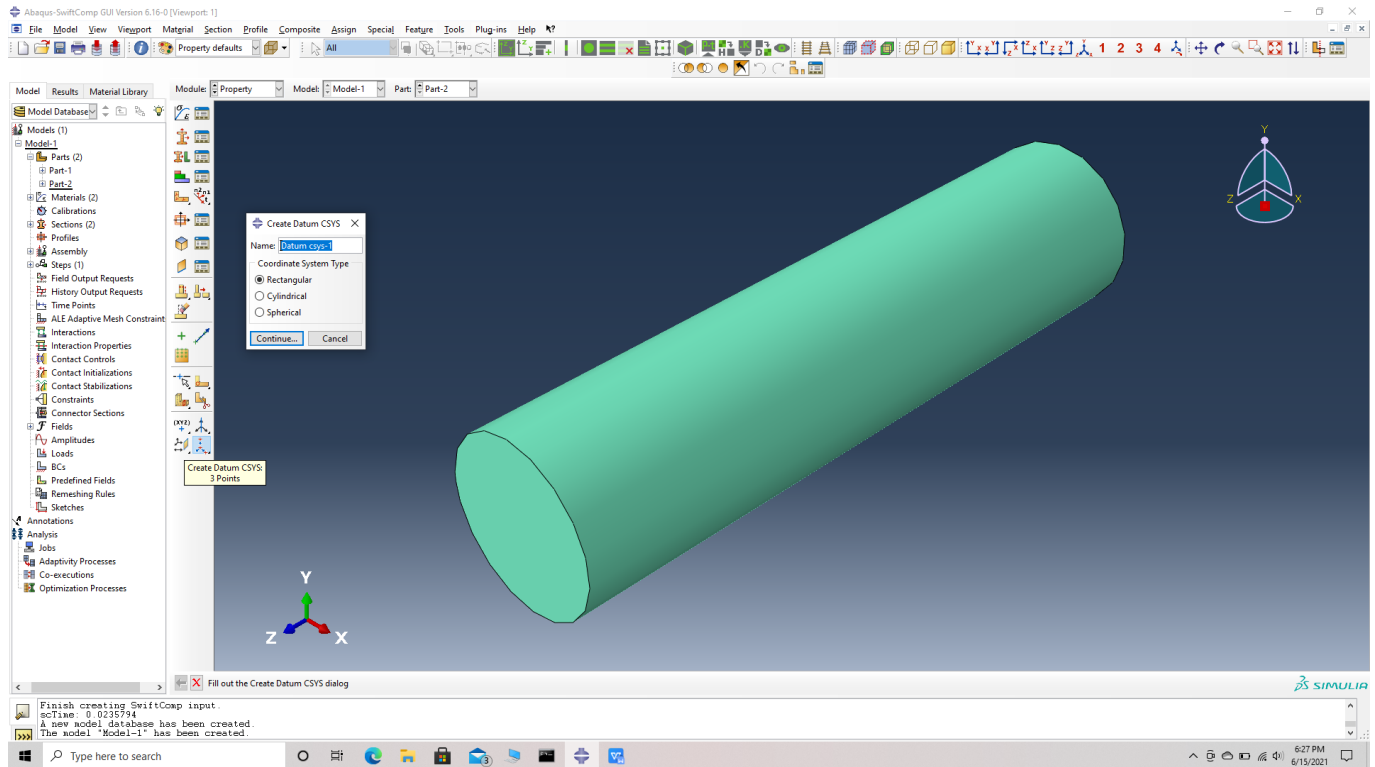


Assign the Section for Set

Step 9. Create a local material coordinate system for the fiber. This is done because, the material coordinates of the fiber do not align with the global material coordinates. Create a

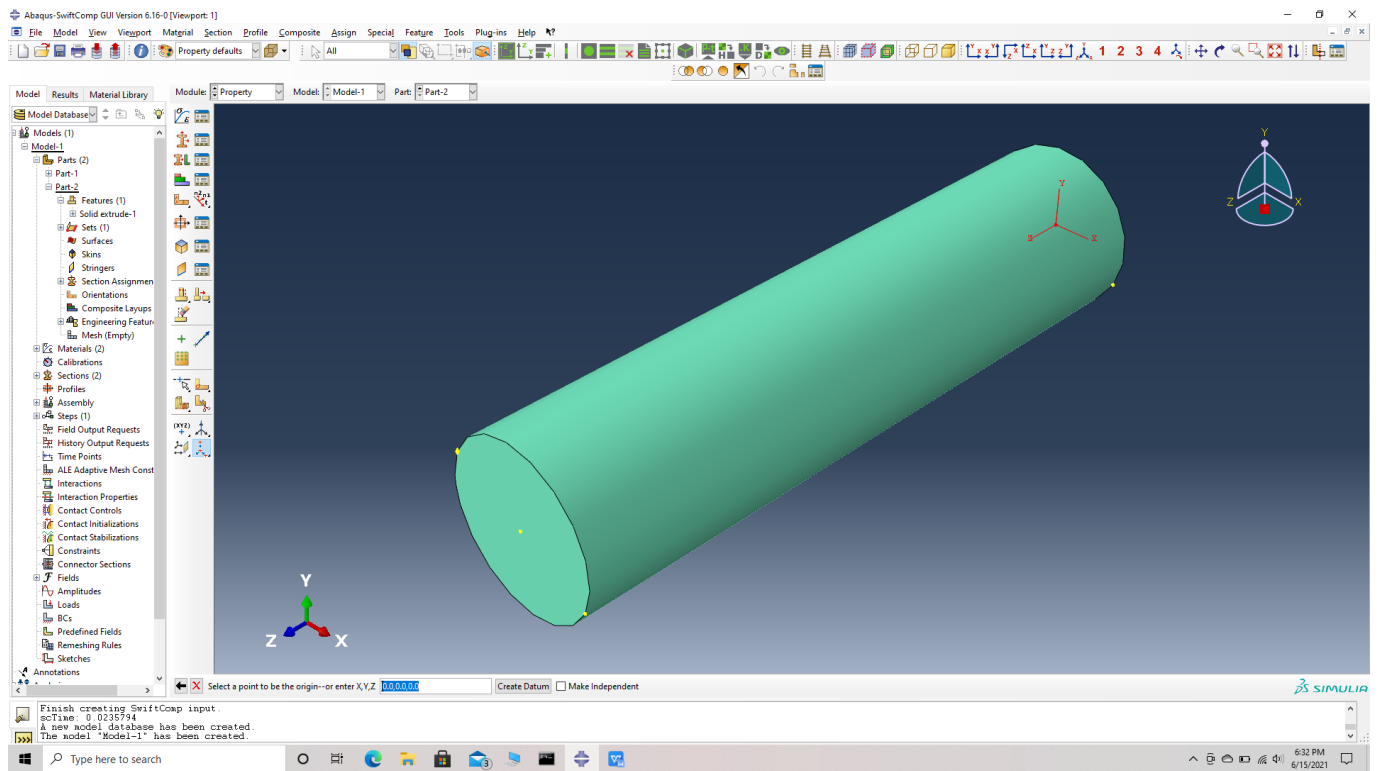
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datum CSYS with three points-> select a rectangular system -> choose the origin which is also the center of a face of the fiber cylinder, as the first point i.e a point on the origin-> choose the center of the opposite face as the second point, i.e a point on the x axis -> choose a point on the circumference of the opposite face whose center is the second point, i.e a point on the x-y plane -> create datum. Note we can randomly choose a point on the second surface to be a point on the x-y plane if the material properties along the y and z axes are equal.

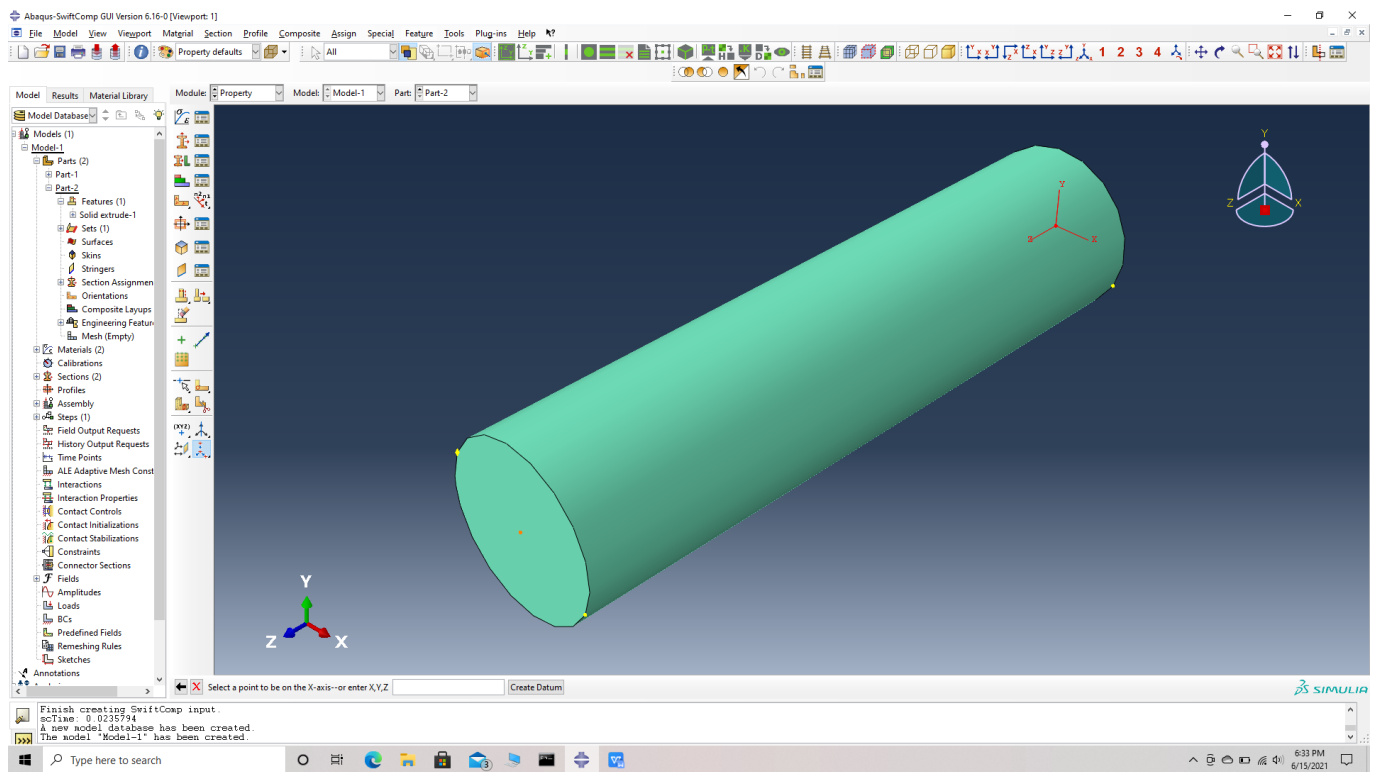


Create datum CSYS

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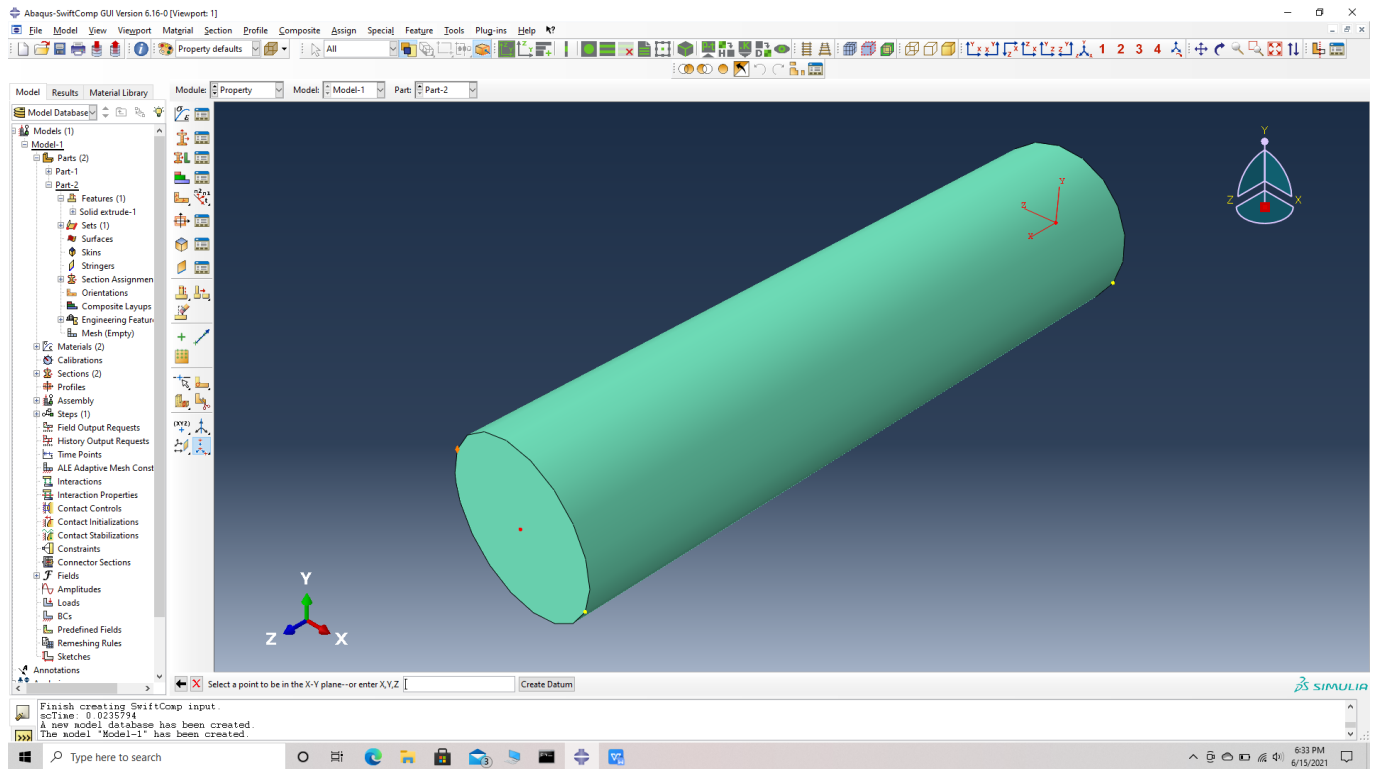


Choose a point as origin

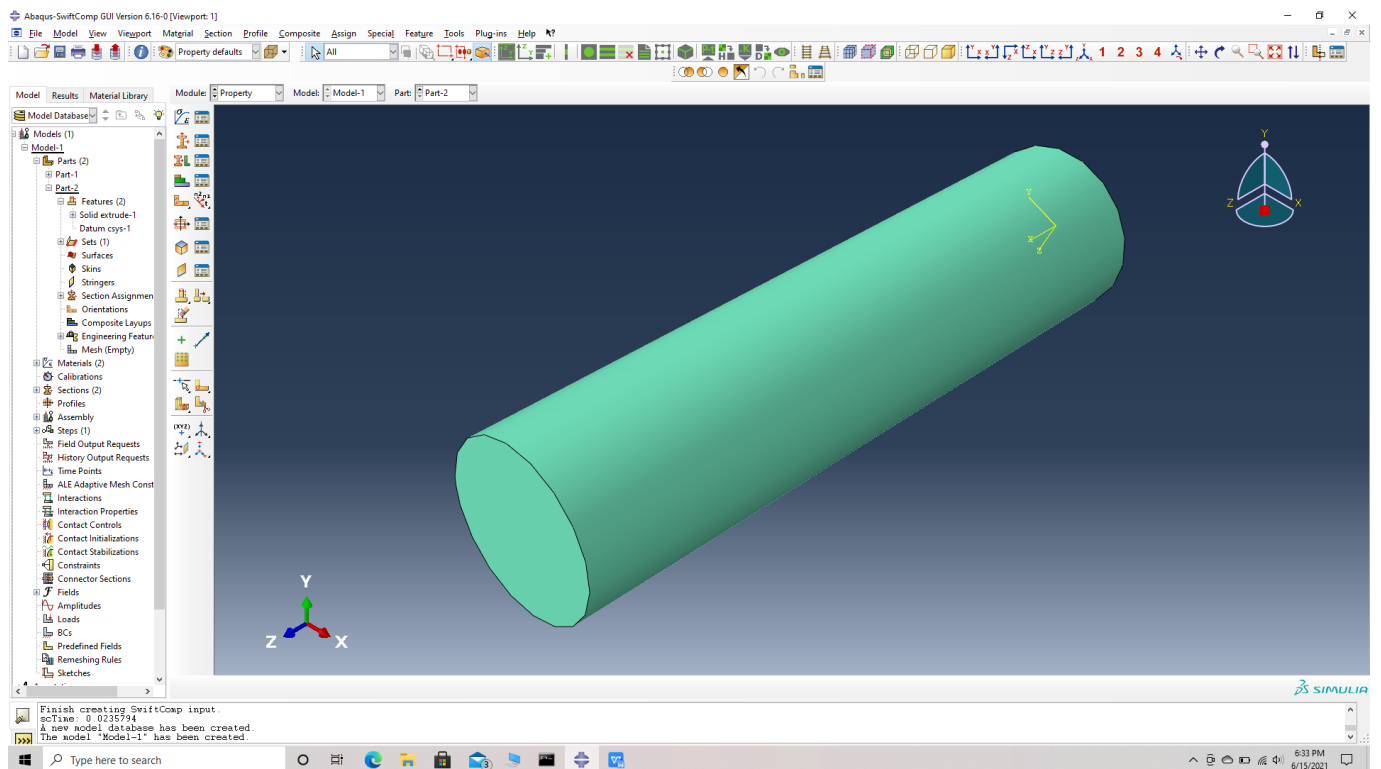


Choose a point on the x axis

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Choose a point on the x-y plane

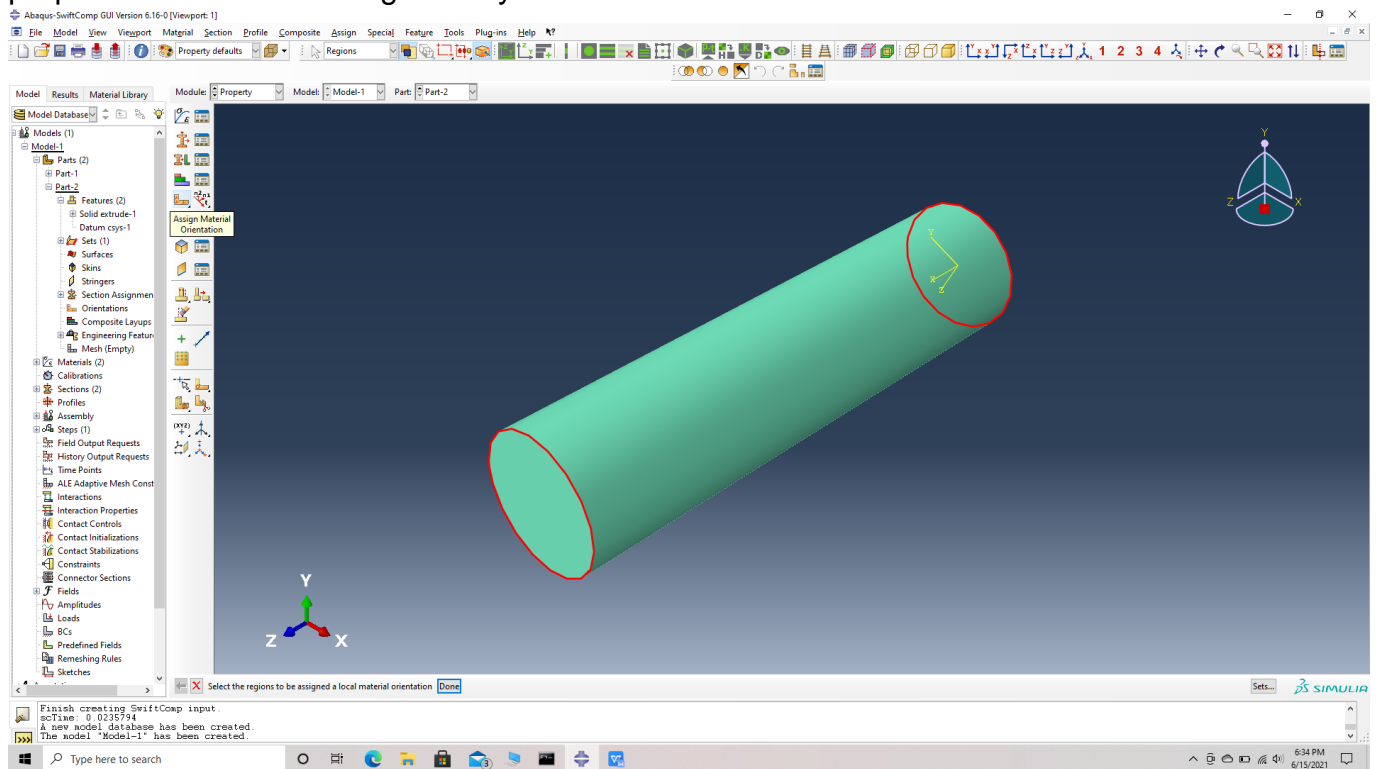


New datum

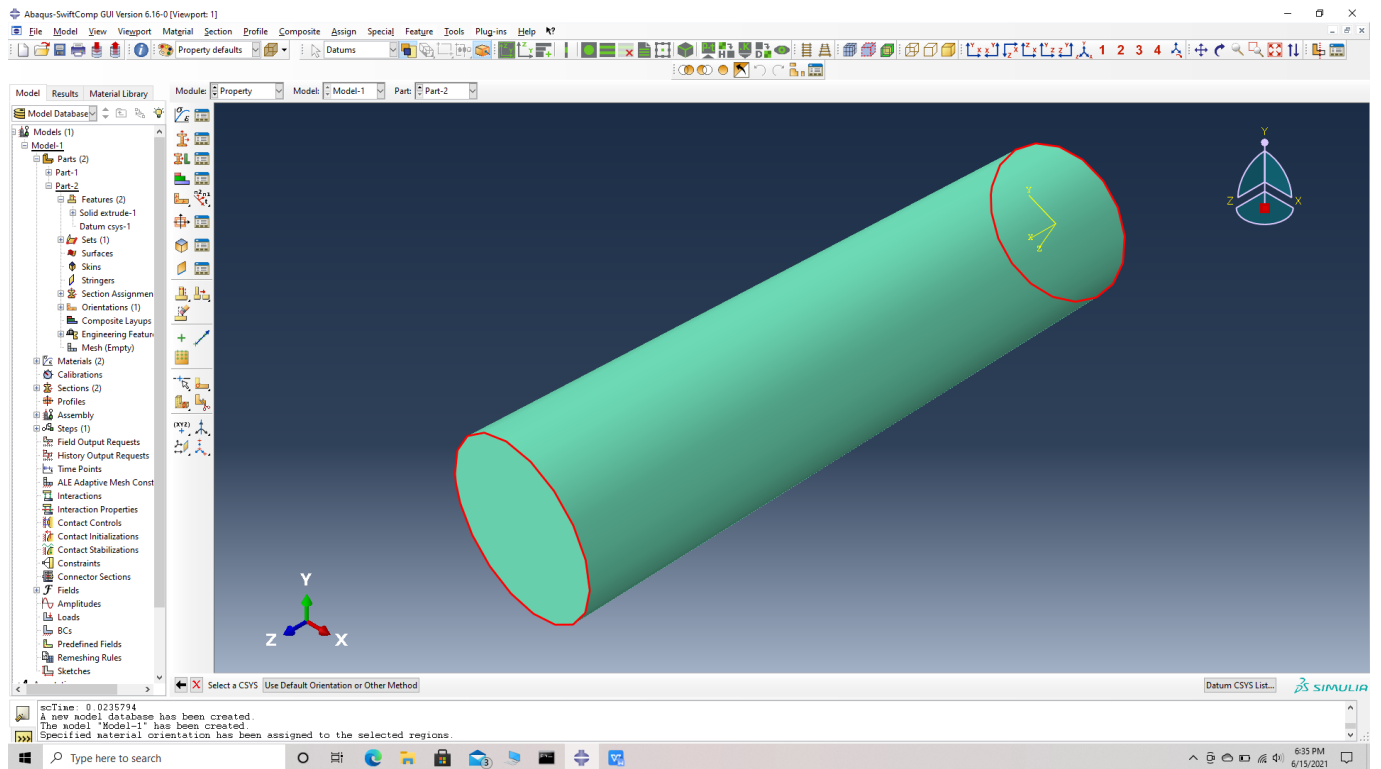
Step 10. Go to assign material orientation option and select the fiber part -> Done -> Choose Datum CSYS list -> Datum CSYS 1 -> ok -> Make sure the orientation of the fiber material

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properties match the fiber geometry and select OK.

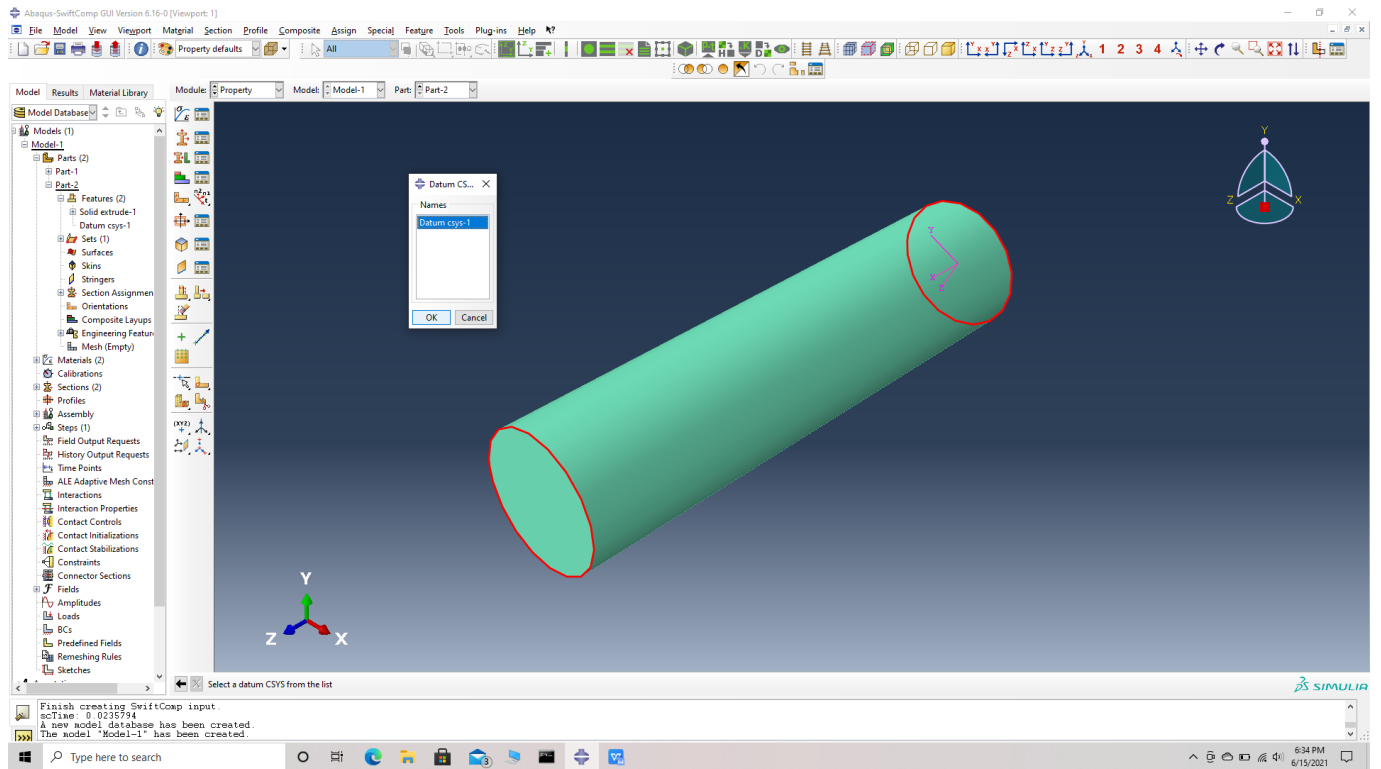


Assign material orientation

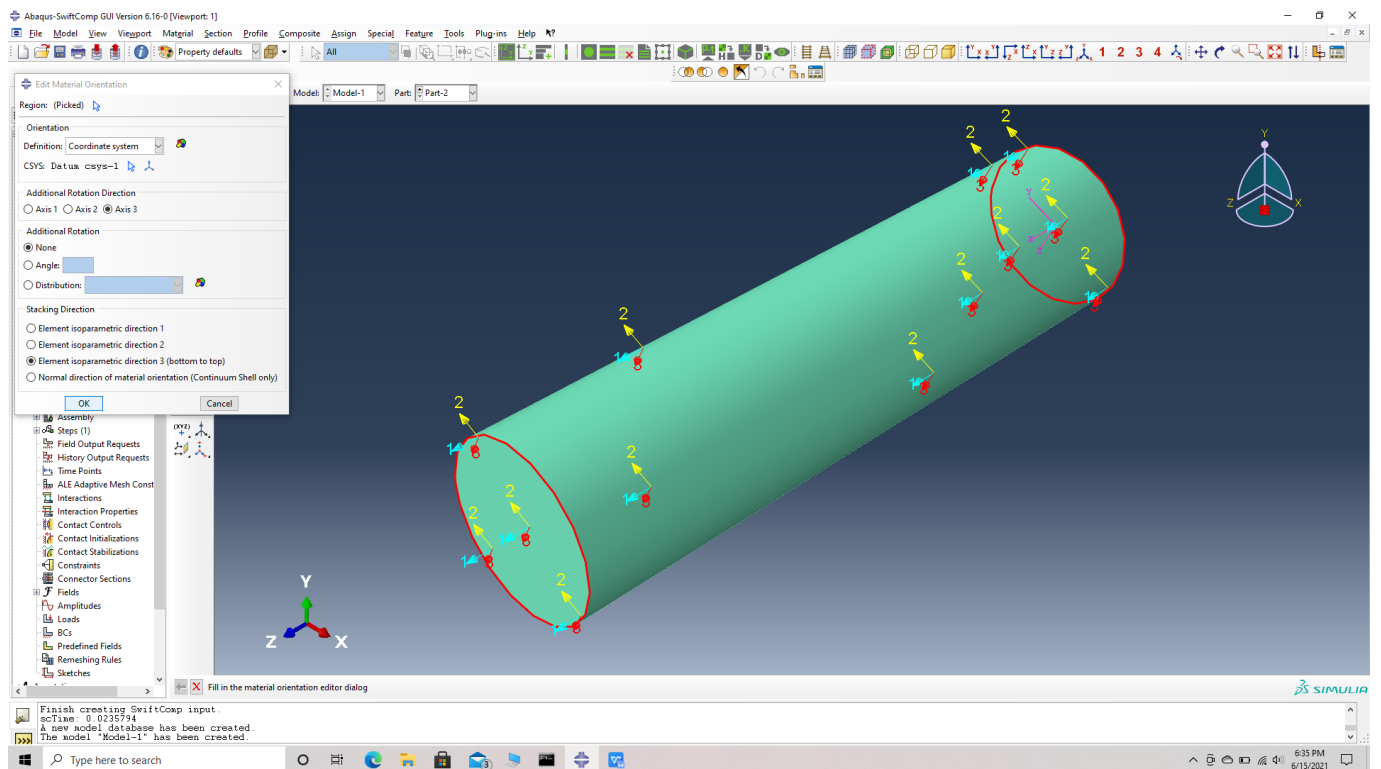


Choose the part and the datum CSYS list at the bottom

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Choose the datum CSYS 1

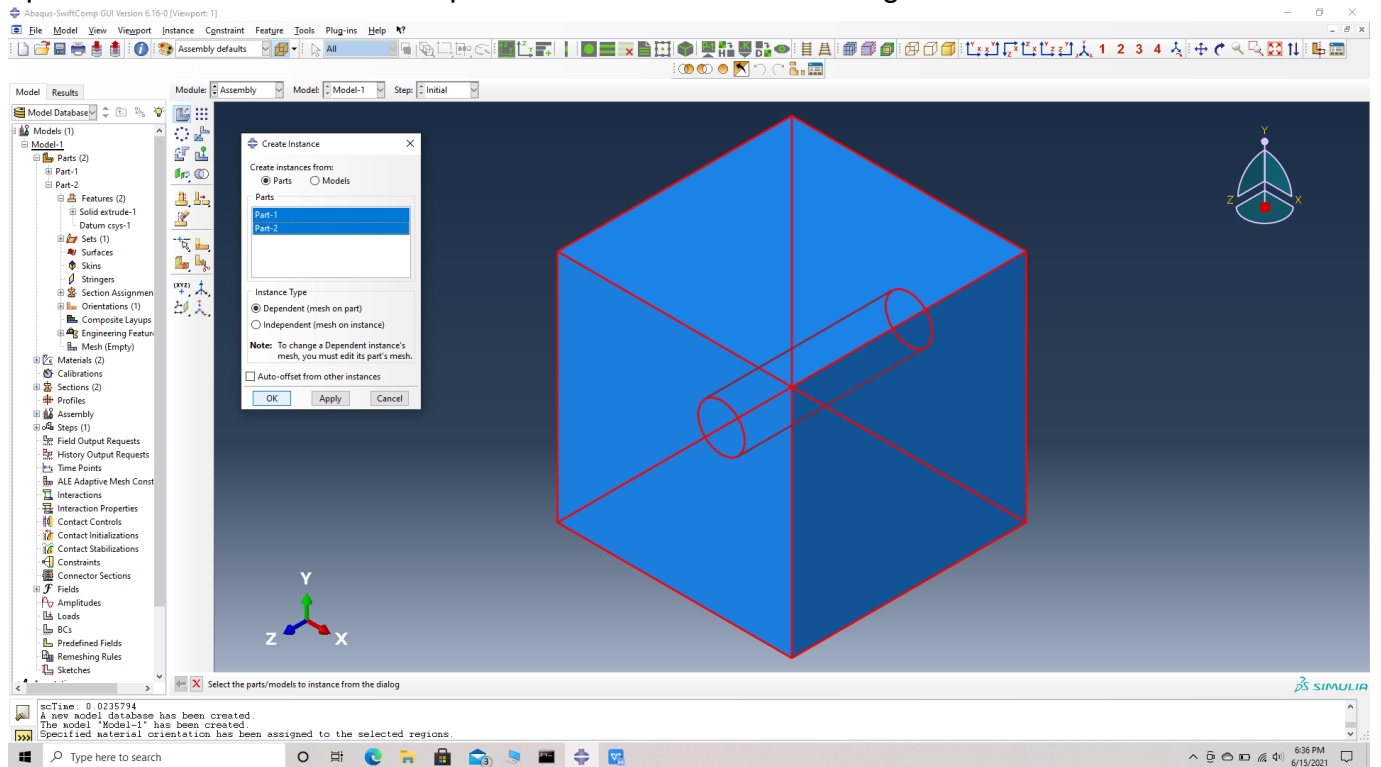


Confirm the orientation

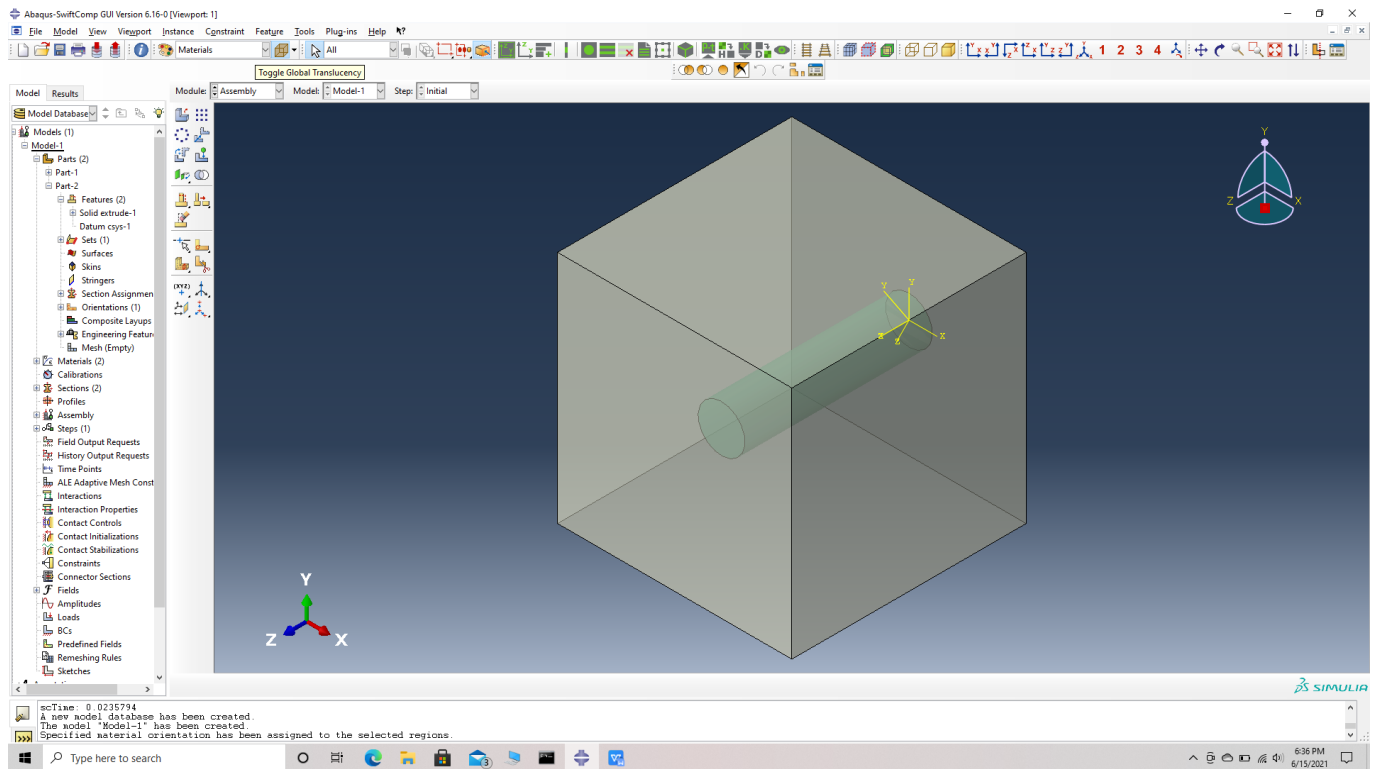
Step 11. Go to assembly -> create instance -> select both parts, single fiber and matrix unit cell -> Dependent Instance type -> O.K. Use the toggle global transparency option and the view

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options on the tool bar at the top to see the fiber and matrix together.



Single fiber assembly



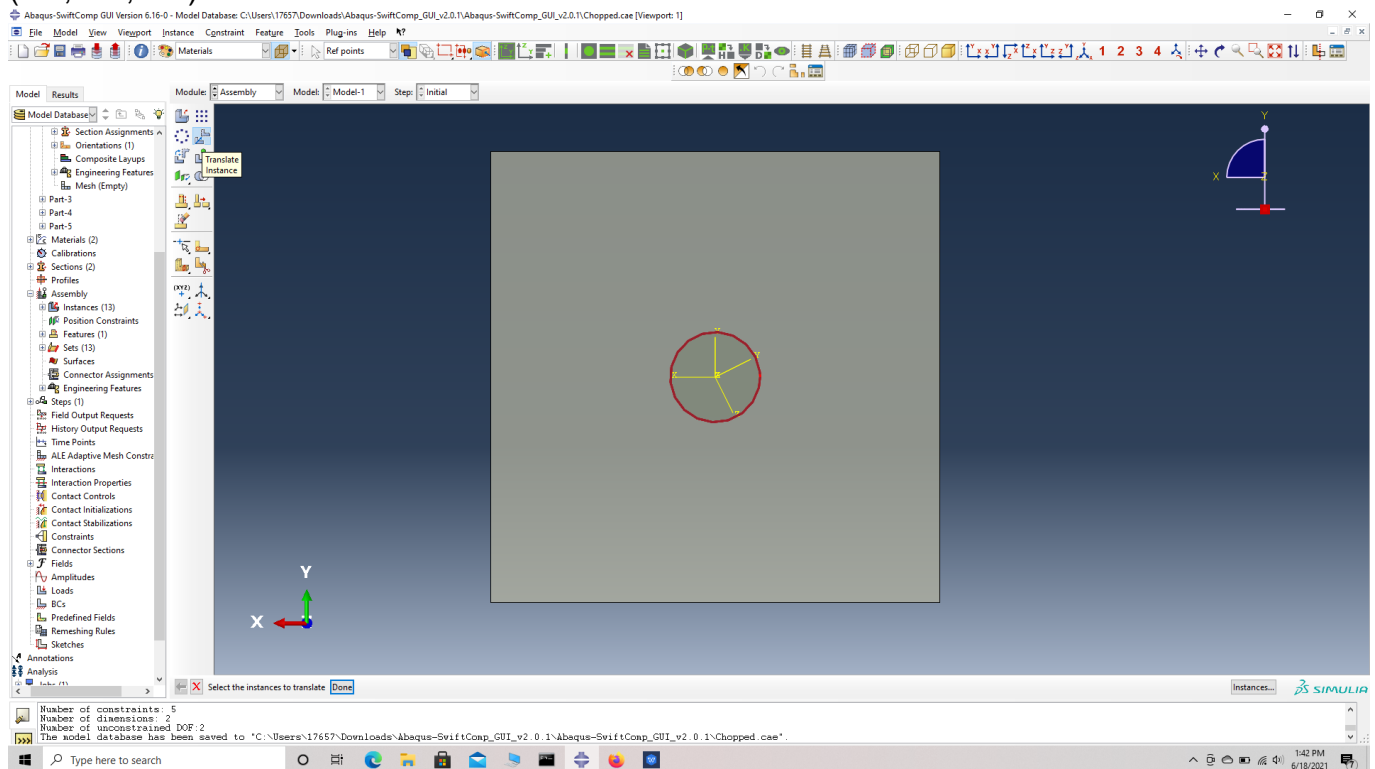
Transparency

Step 12. We will use the following guidelines to orient the fibers.

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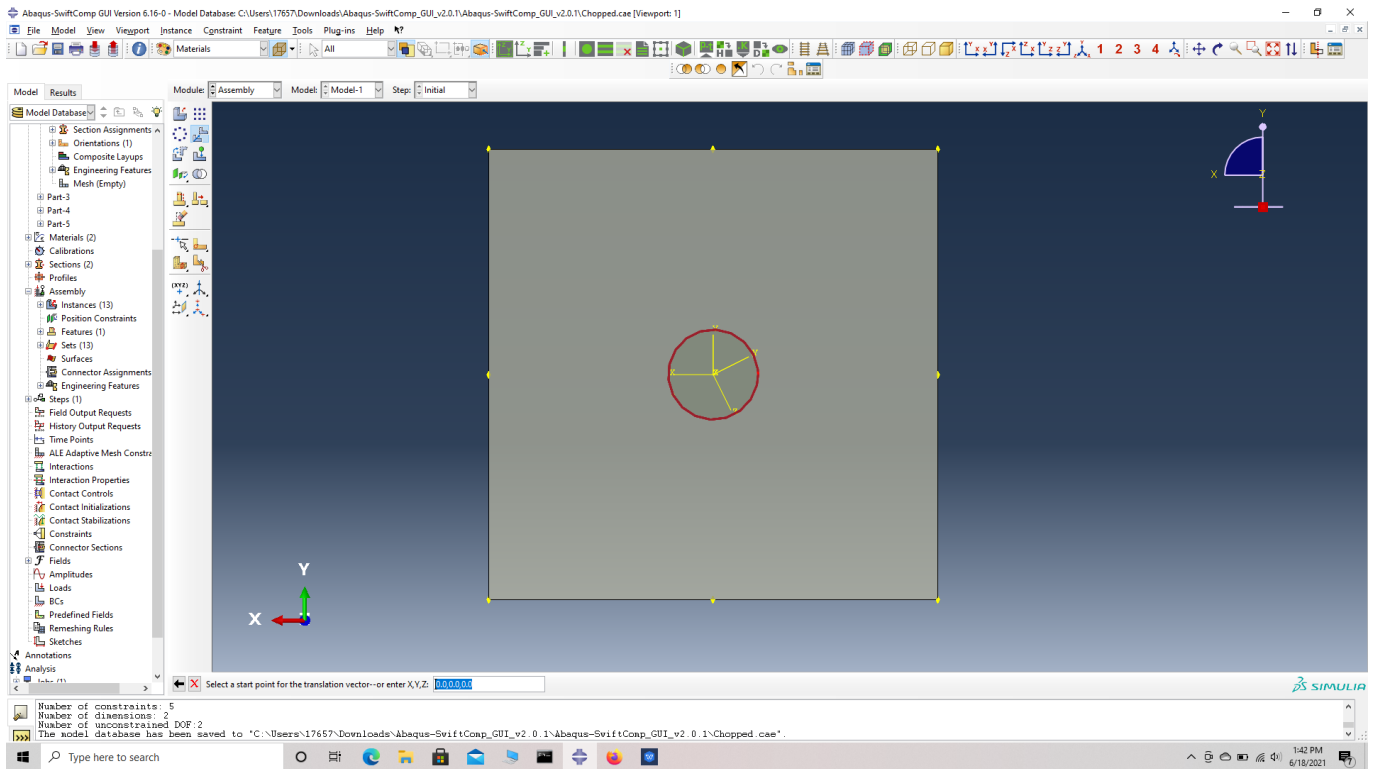
- i) Translation- Translate instance -> choose the fiber instance -> choose start points for the translation vector -> (0,0,0) -> choose end points for the translation vector -> (x- coordinate, y- coordinate, z- coordinate). The instance can be translated across all three axes simultaneously.
- ii) Rotation- Rotate instance -> choose the fiber instance -> choose start points for the axis of rotation -> (0,0,0) -> choose end points for the axis of rotation -> (positive coordinate for the axis, zero for the other two axes). The instance can be rotated across any one axis at a time. We will rotate along the x axis first followed by the y axis and end with z axis.

Step 13. Translate the first fiber, Translate instance -> choose the fiber instance -> choose start points for the translation vector -> (0,0,0) -> choose end points for the translation vector -> (2.9, 3.4, 1.0).

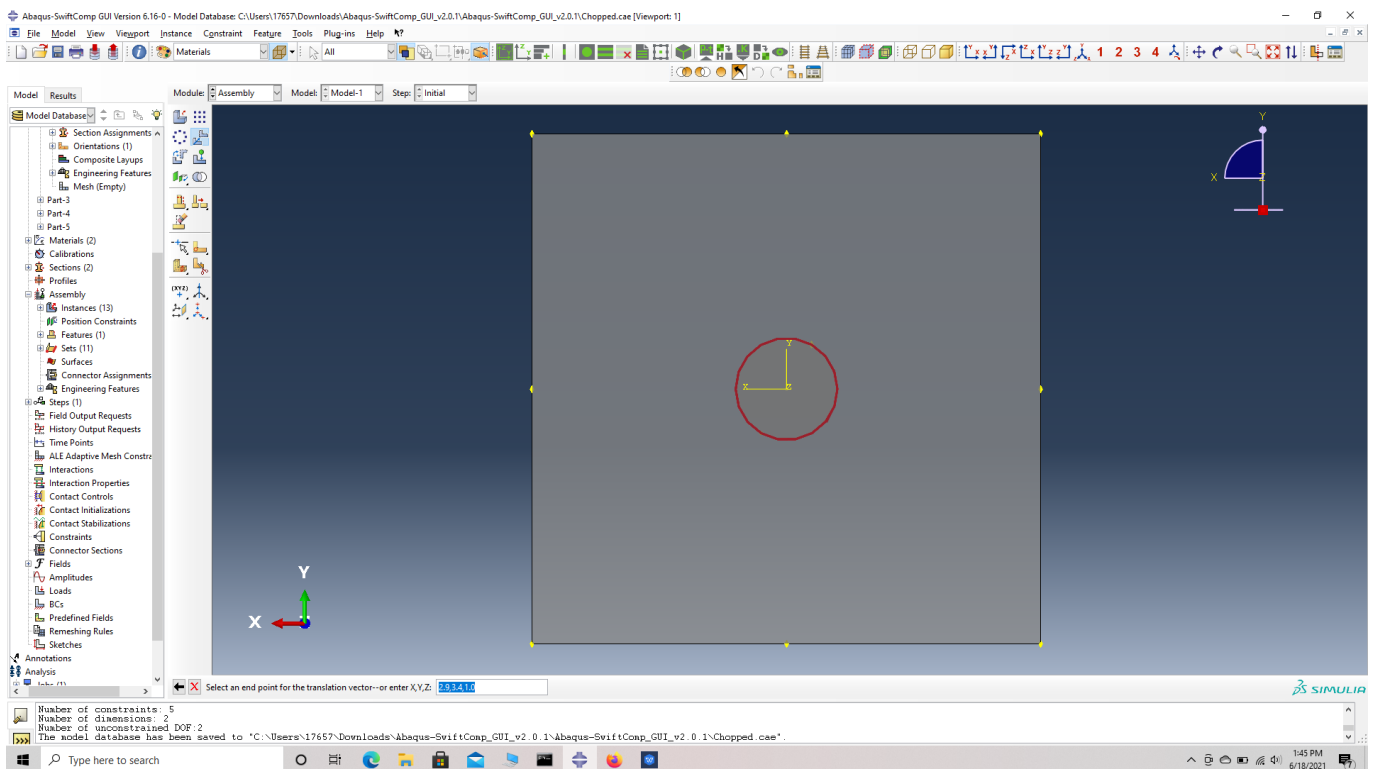


Translate instance

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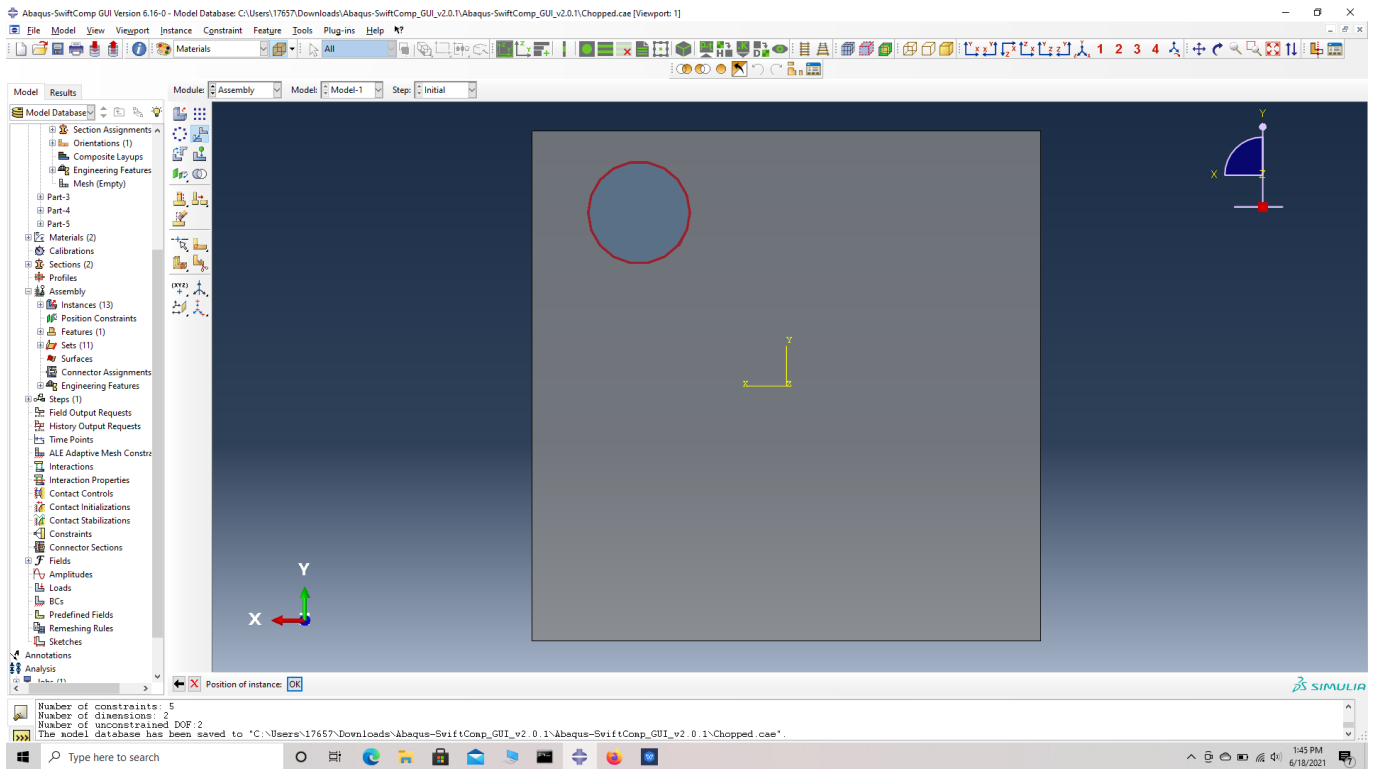


choose start points for the translation vector



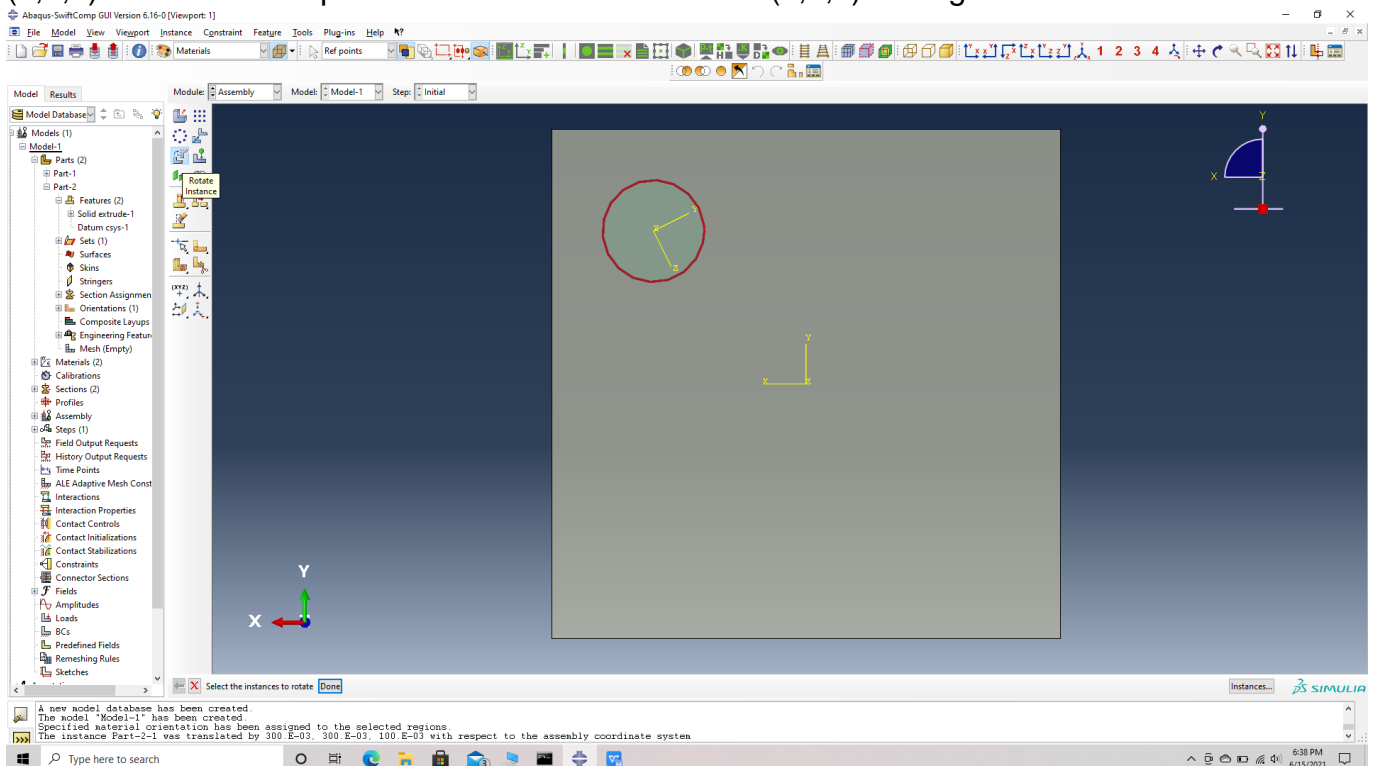
choose end points for the translation vector

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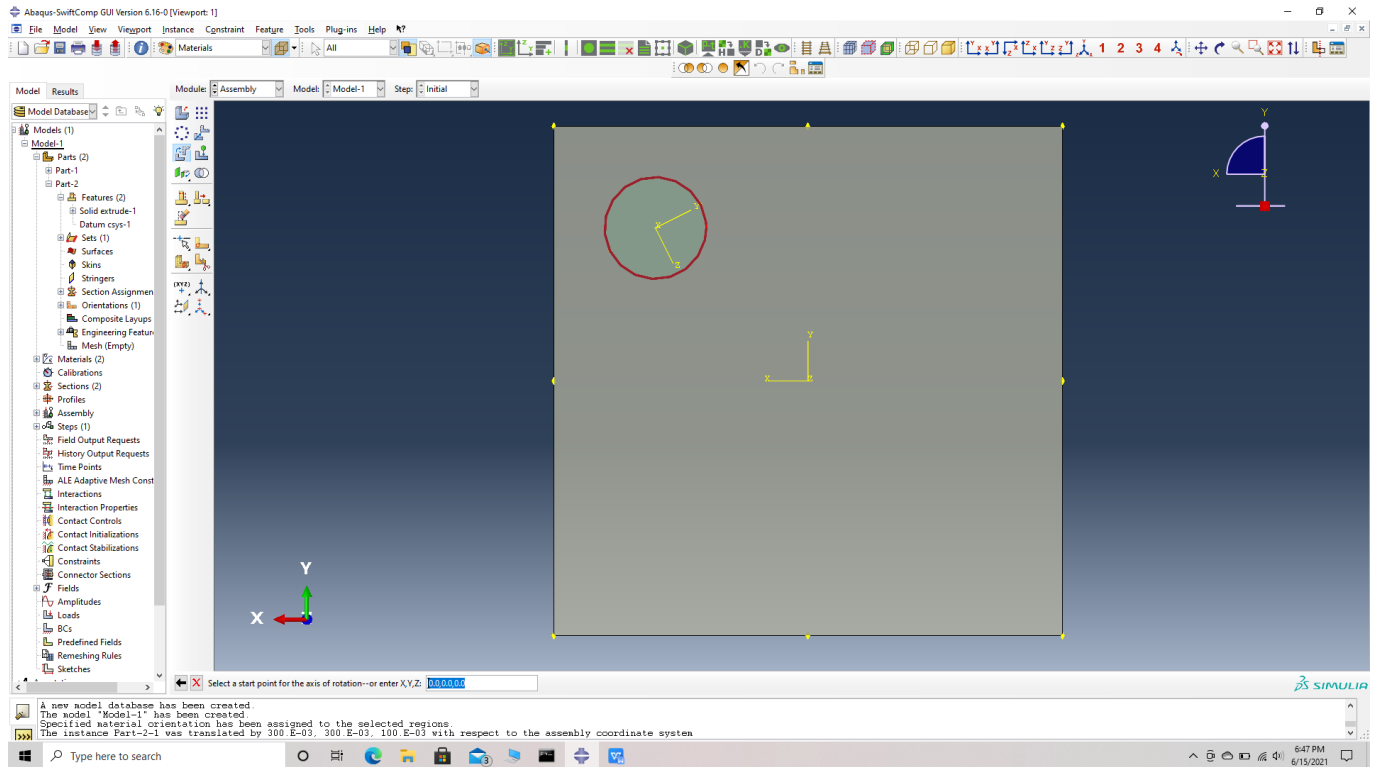
Translated fiber

]] # Step 14. Rotate the first fiber 5 degrees along X followed by 5 degrees along Y. For X, Rotate instance -> choose the fiber instance -> choose start points for the axis of rotation -> (0,0,0) -> choose end points for the axis of rotation -> (1,0,0) -> Angle of rotation -> -3. For Y, Rotate instance -> choose the fiber instance -> choose start points for the axis of rotation -> (0,0,0) -> choose end points for the axis of rotation -> (0,1,0) -> Angle of rotation -> -5.

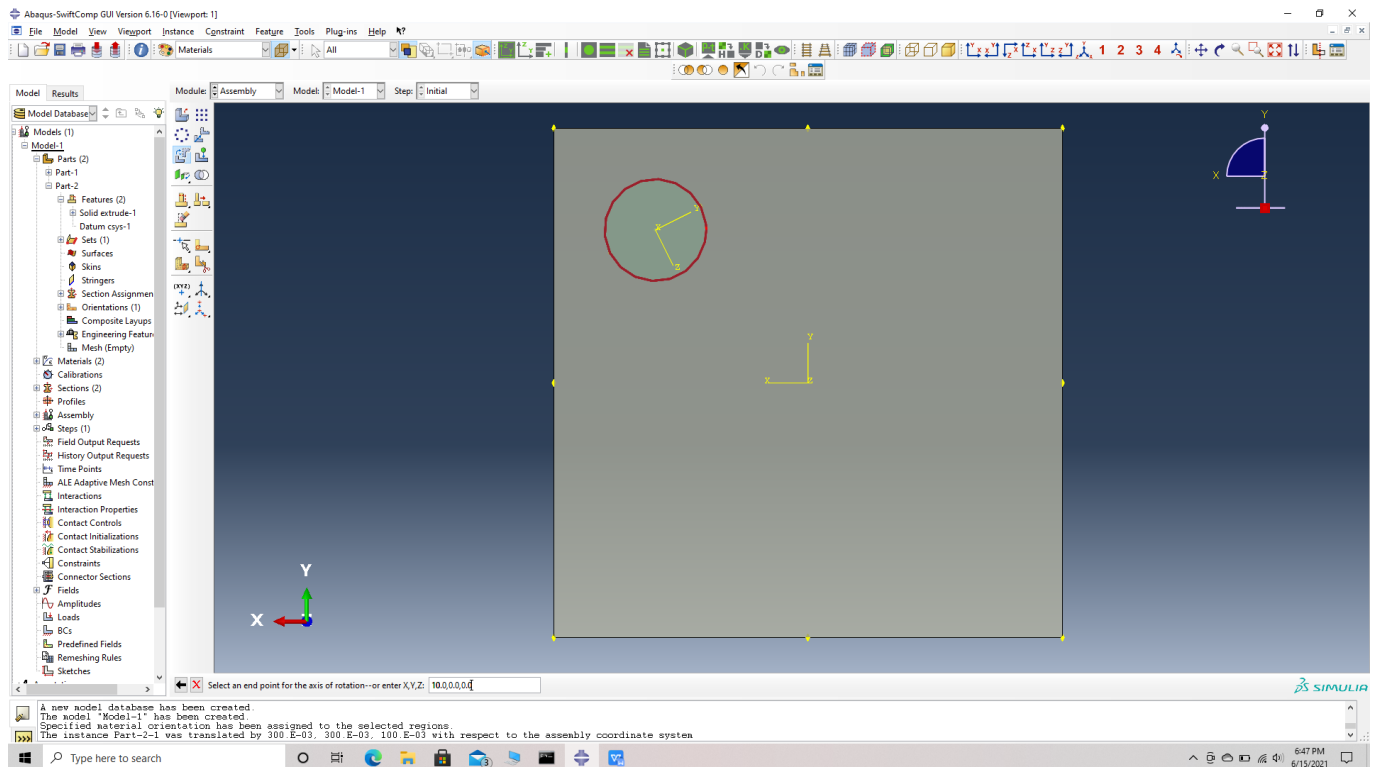


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Rotate instance

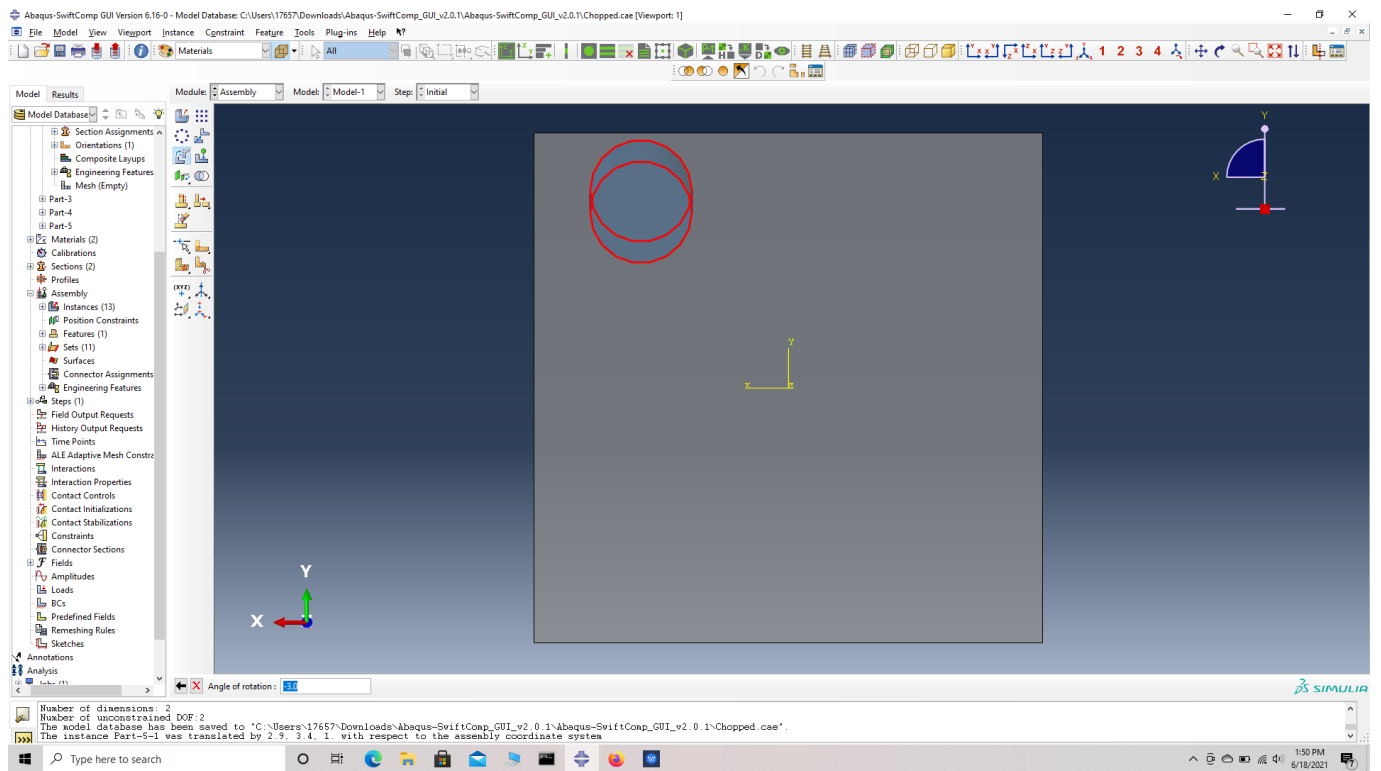


choose start points for the axis of rotation

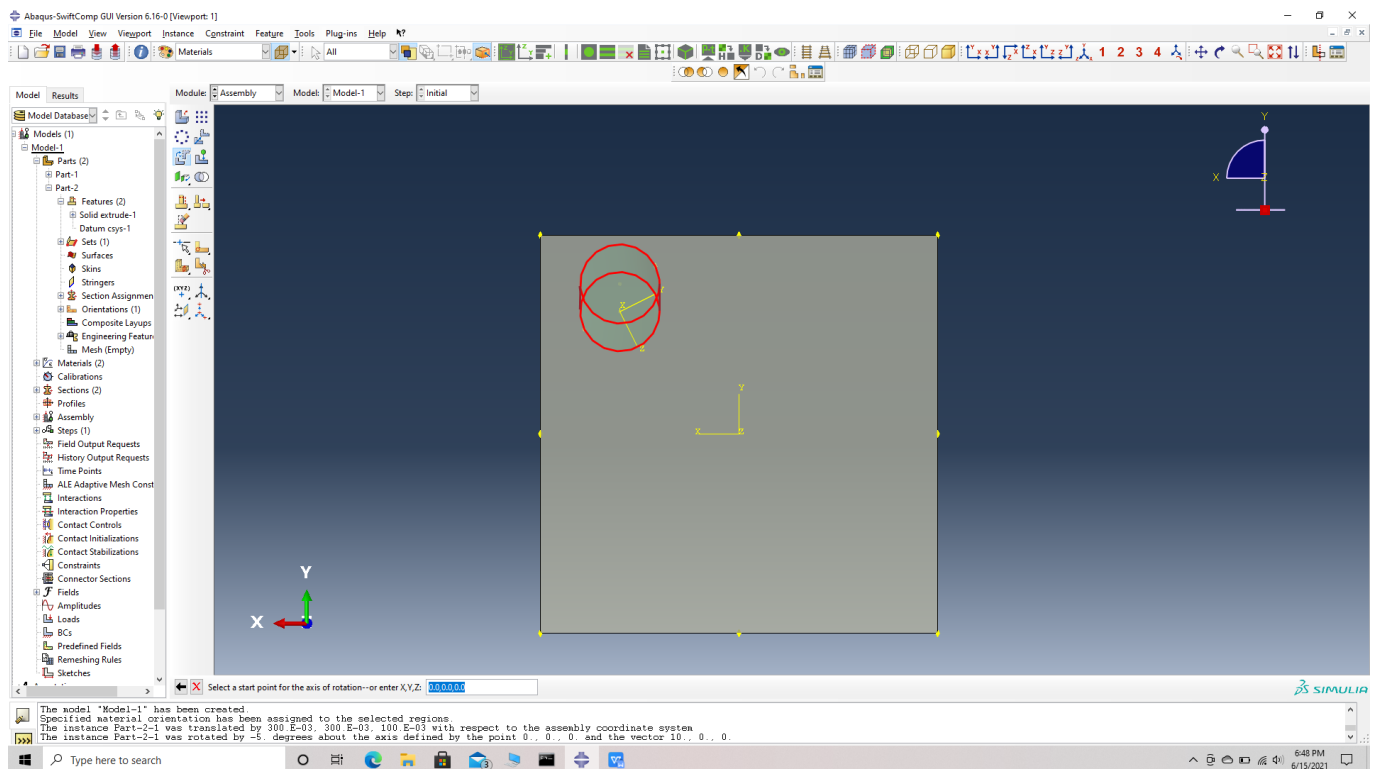


choose end points for the axis of rotation

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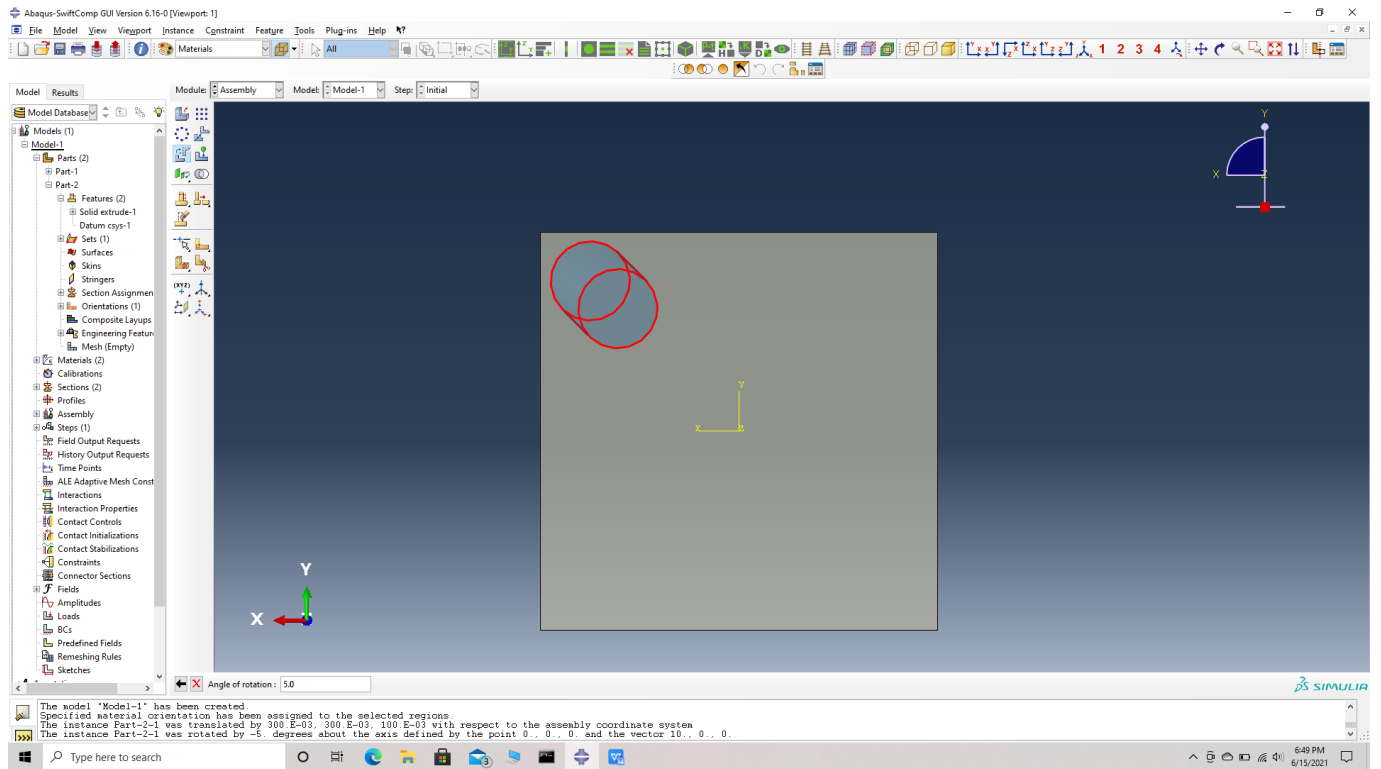


degrees of rotation



Fiber rotated about X and moving on to Y axis

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Fiber rotated about X and also Y

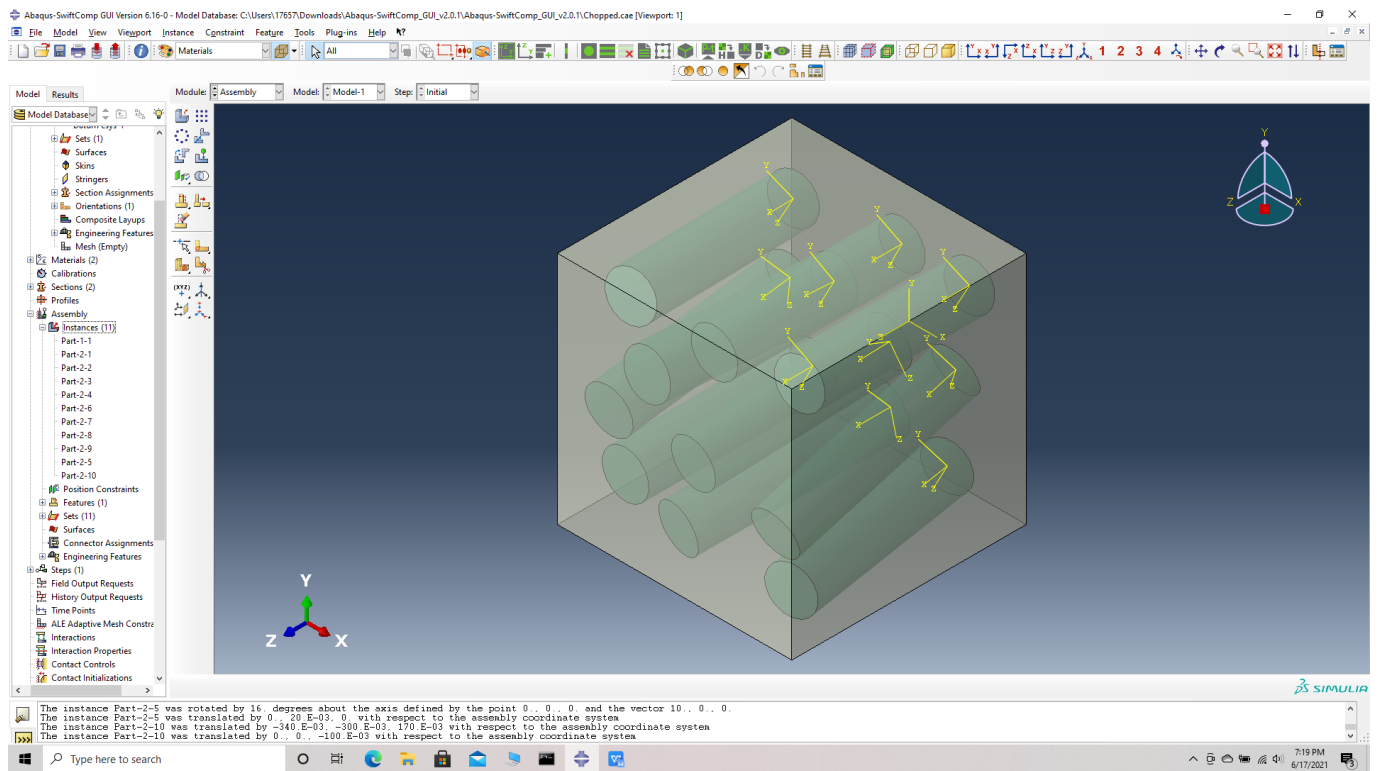
Step 15. Similarly Translate and rotate all fibers according to the table provided.

The fiber orientation is given by fiber translation along the three axes (in mm) denoted by X,Y & Z and rotation along the three axes (in °) denoted by θ_x , θ_y , & θ_z .

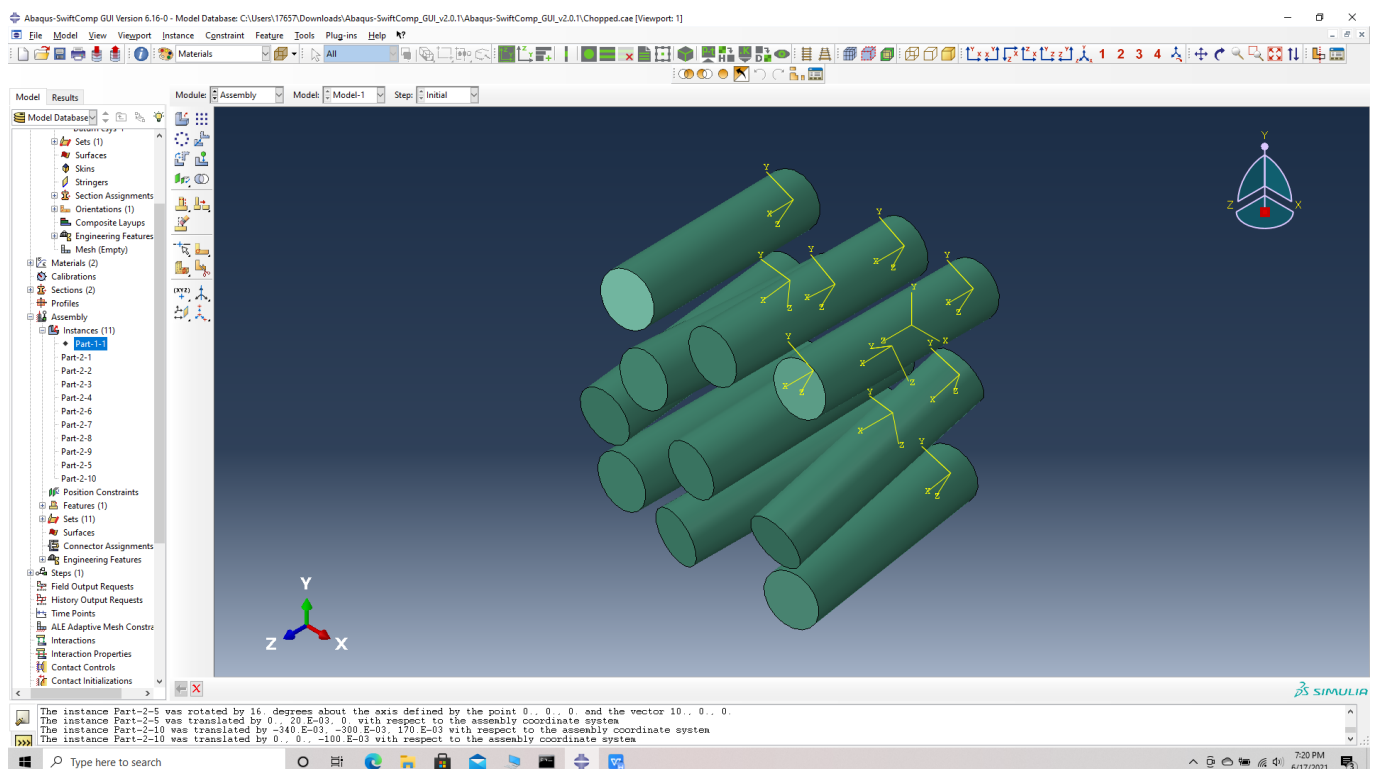
Fiber No	X	Y	Z	θ_x	θ_y	θ_z
1	2.9	3.4	1.0	-3	5	0
2	0.6	3.1	0.8	0	0	0
3	-4.0	3.0	1.0	-6	7	0
4	-1.5	1.5	1.8	-4	0	0
5	3.5	1.1	1.3	16	0	0
6	1.5	1.0	1.7	0	-6	60
7	2.3	-3.7	1.2	0	9	0
8	-1.0	-2.6	1.4	3	-12	30
9	-3.6	1.7	1.4	6	0	16
10	-3.4	-3.0	0.7	0	0	0

Fiber orientation

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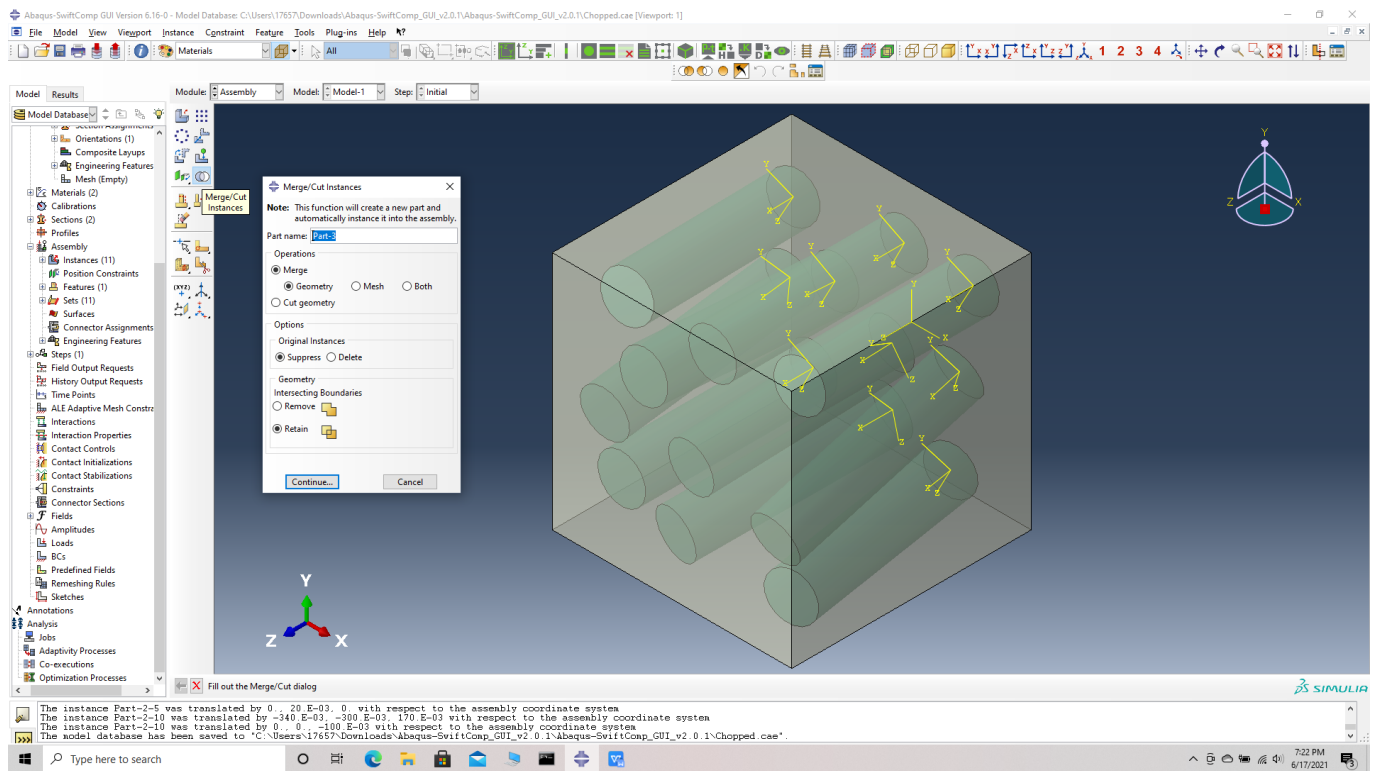
Fibers oriented in matrix unit cell



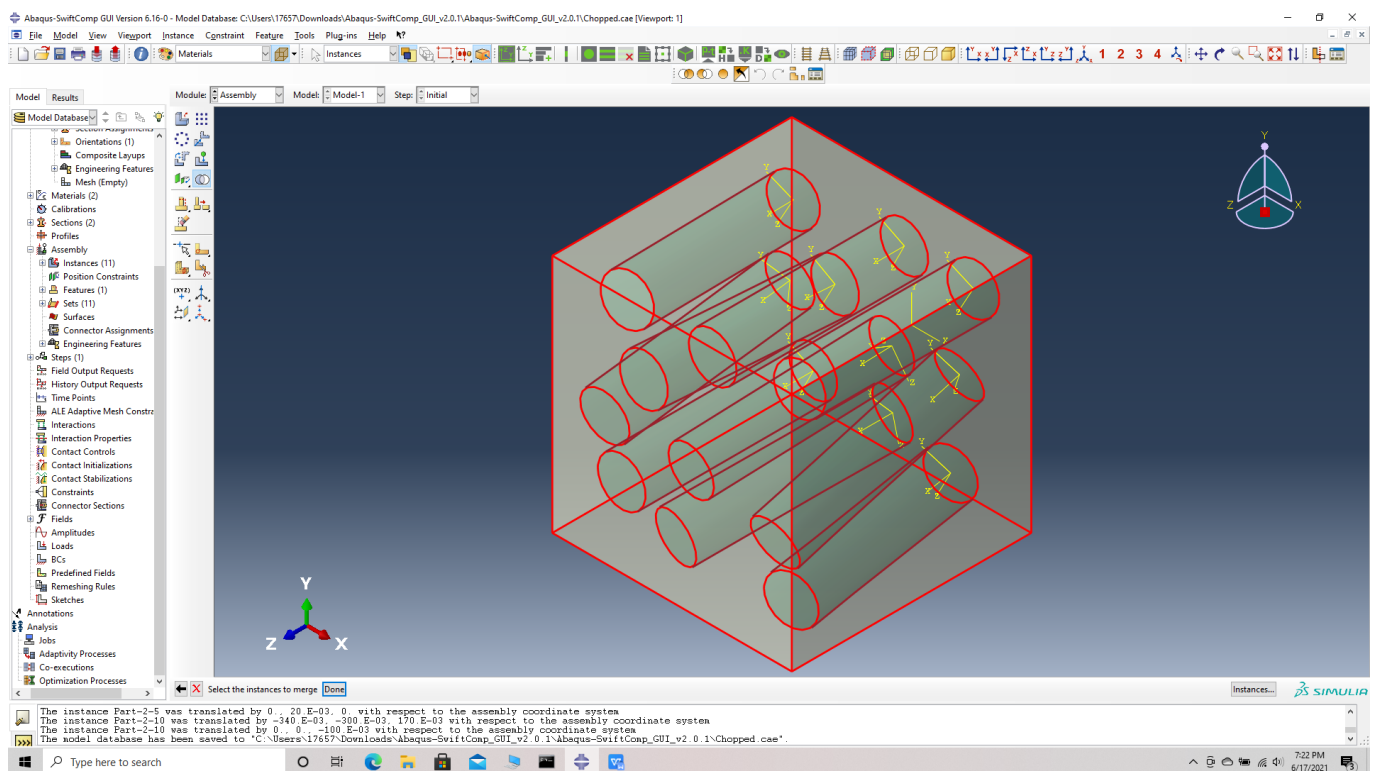
Fibers oriented

Step 16. Merge the parts, Merge/cut instances -> Merge geometry -> suppress instances -> retain boundaries -> continue -> select all instances -> Done.

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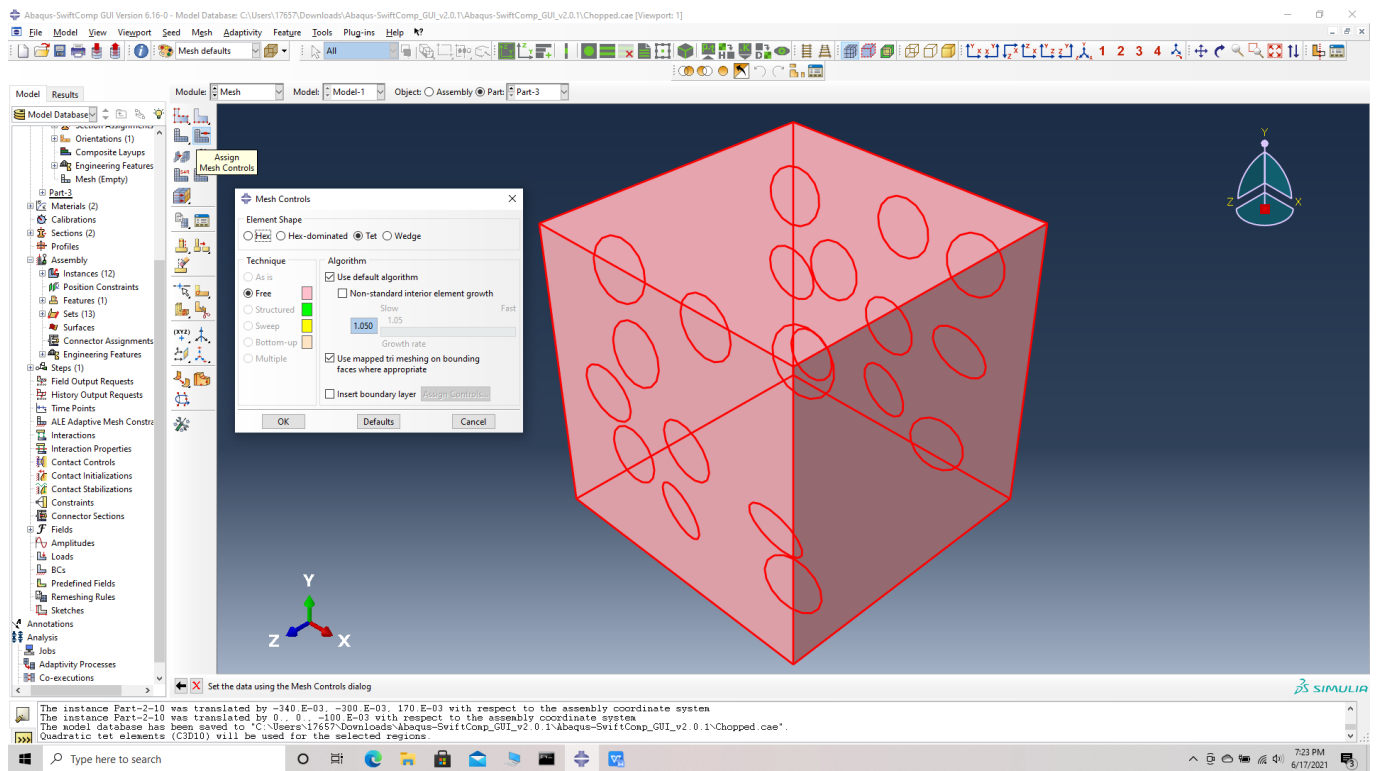
Merge/cut instaces



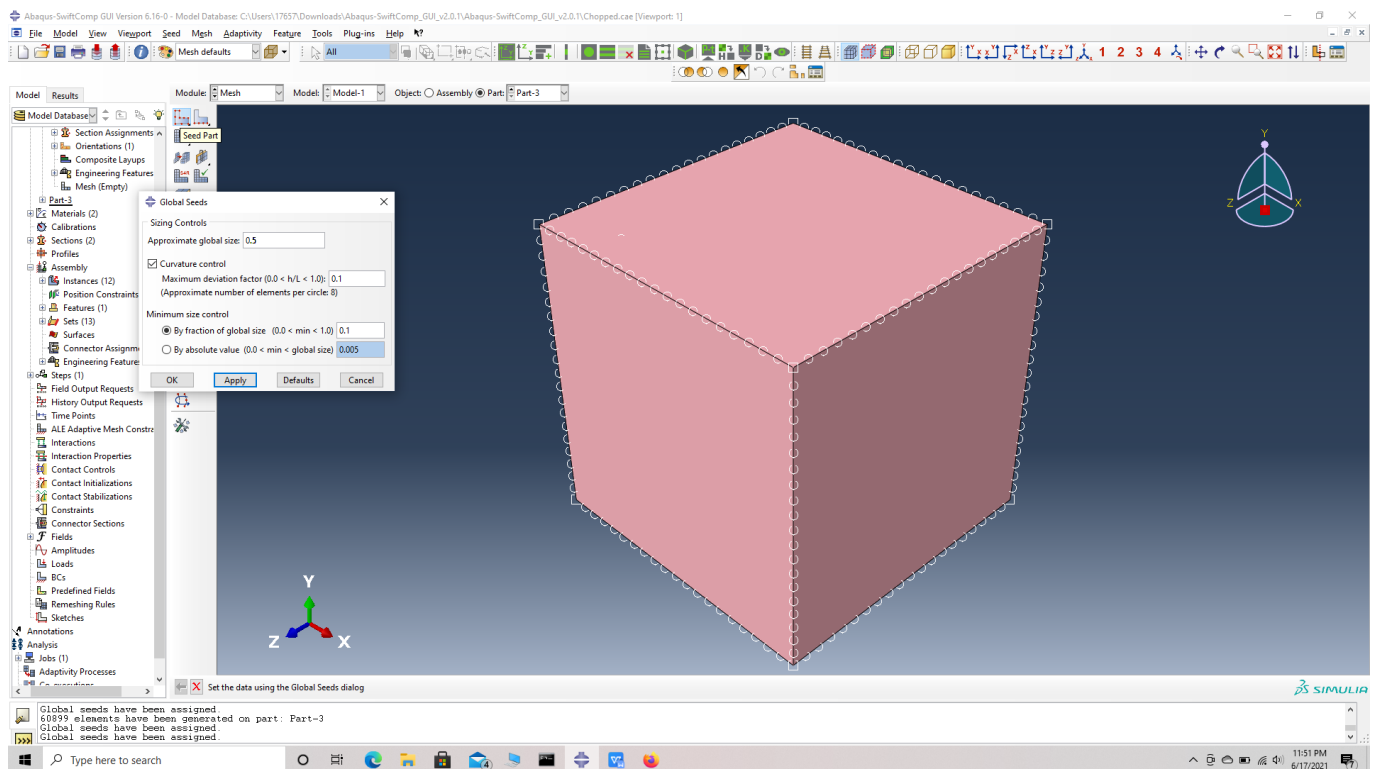
select all instances

Step 17. Mesh options -> Assign mesh controls -> select part -> Tet mesh-> OK -> Seed part -> Global seed size -> 0.5 -> Mesh part -> OK.

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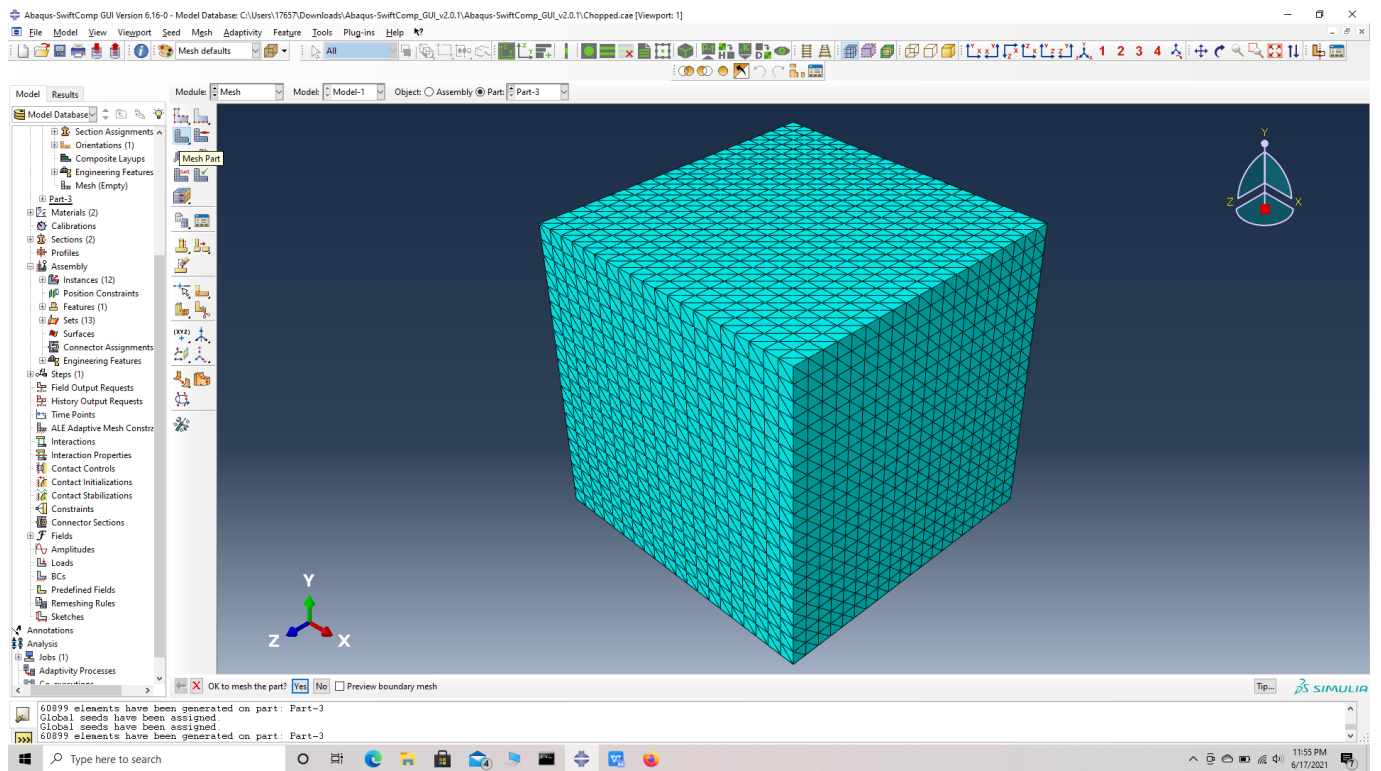


Assign mesh controls -Tet mesh



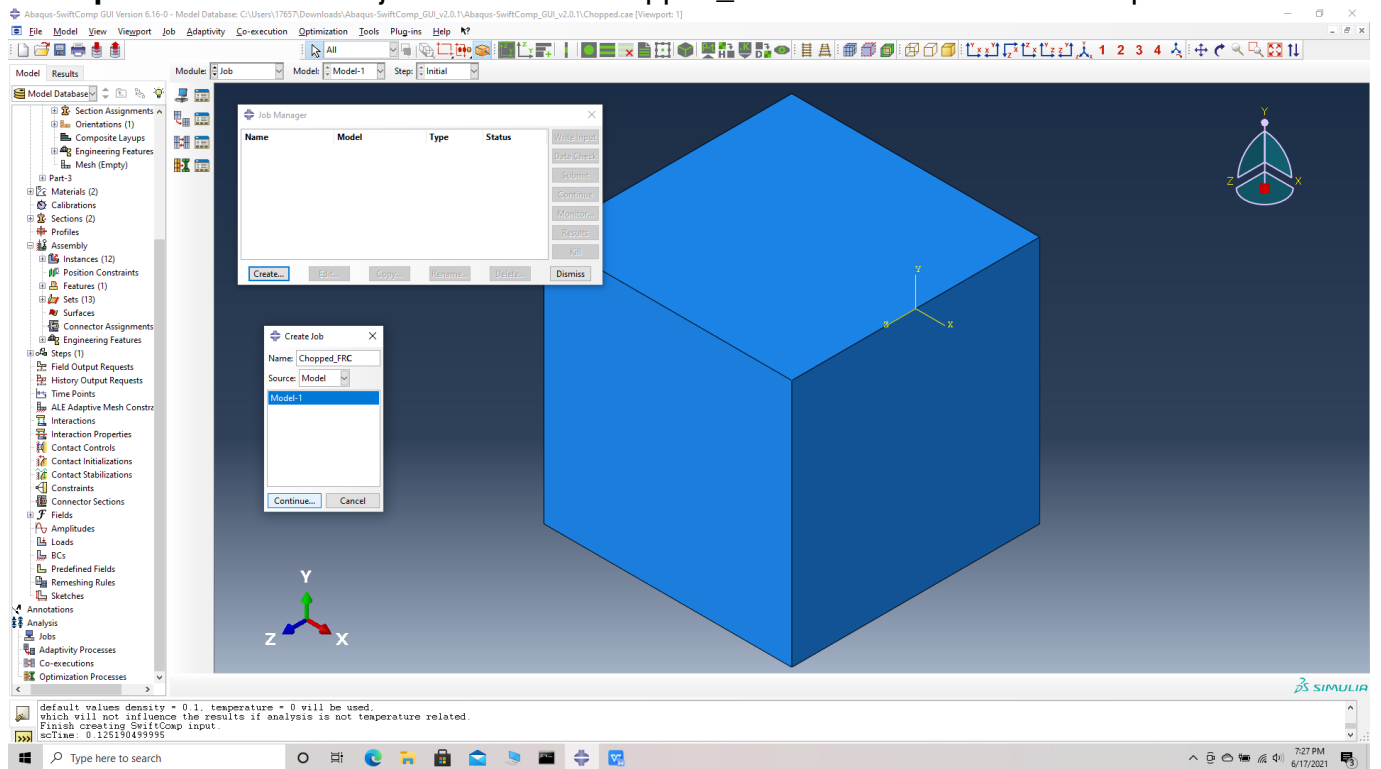
Seed part with Global seed size - 0.5

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Meshed part

Step 18. Job -> Create job -> rename Chopped_FRC -> Continue -> Write input.

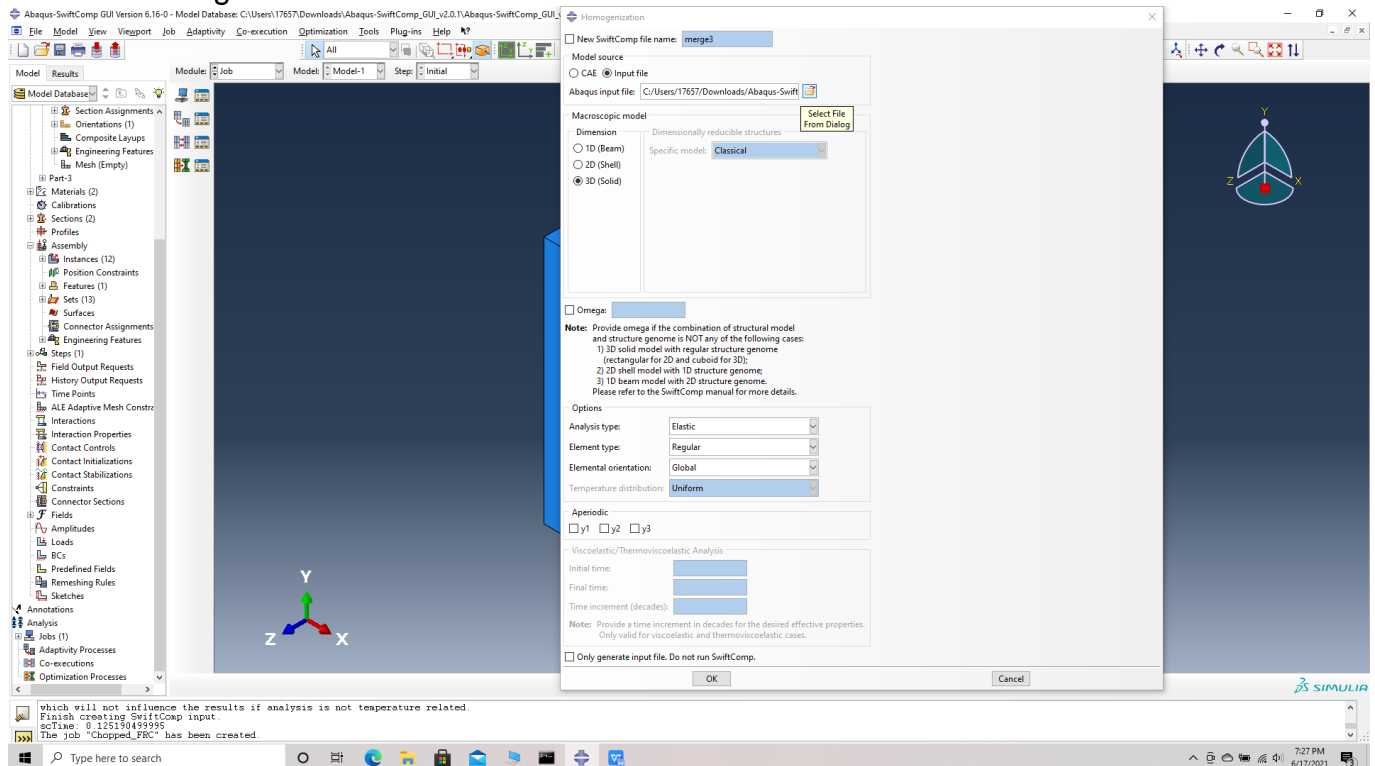


Create job

Step 19. To the effective Elastic properties. we click on Homogenization and select Elastic in

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Analysis Type. Homogenize the part preferably as a 3D solid using the Homogenization via input file option to get the final results. The Homogenization via input file option is used when we have to assign material orientations.



Homogenization

Step 20. Results the effective Elastic properties of the chopped fiber reinforced composite are provided in the table below.

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References